

UPPAAL - Present and Future

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Outline:

- 1 Model-checking Timed Automata
- 2 Internal Optimizations
- 3 Applications: Protocols & Controllers
- 4 Extensions of the Modeling Language

Collaborators

@ UPPsala

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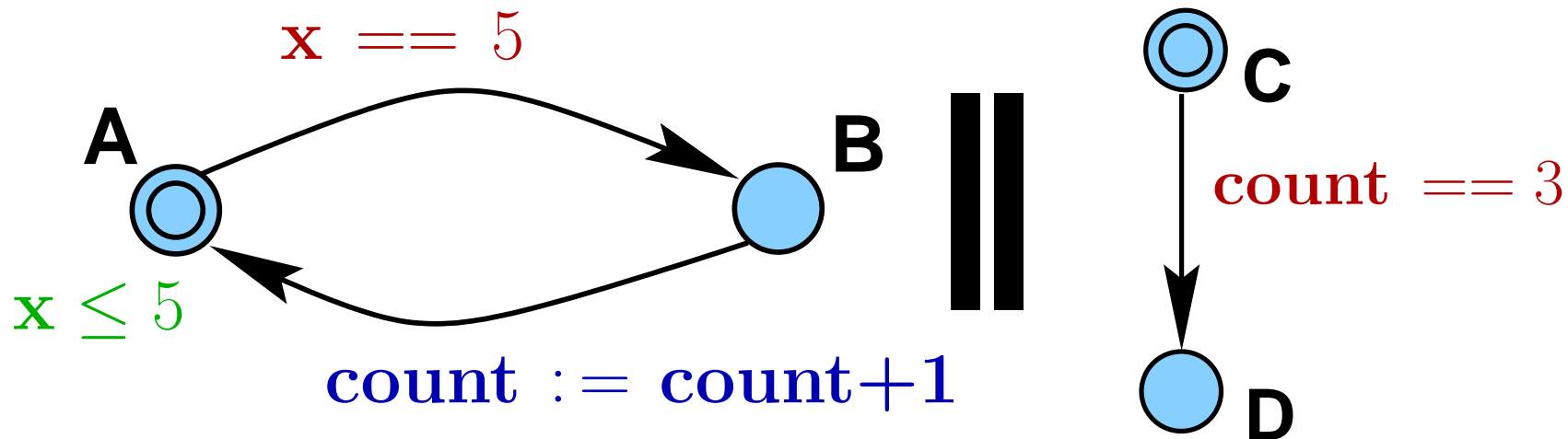
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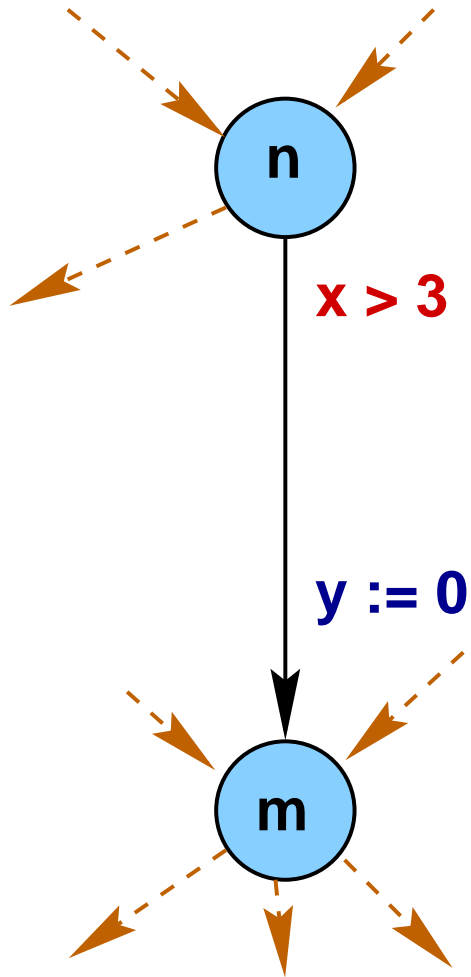
UPPAAL: Model checking Timed Automata



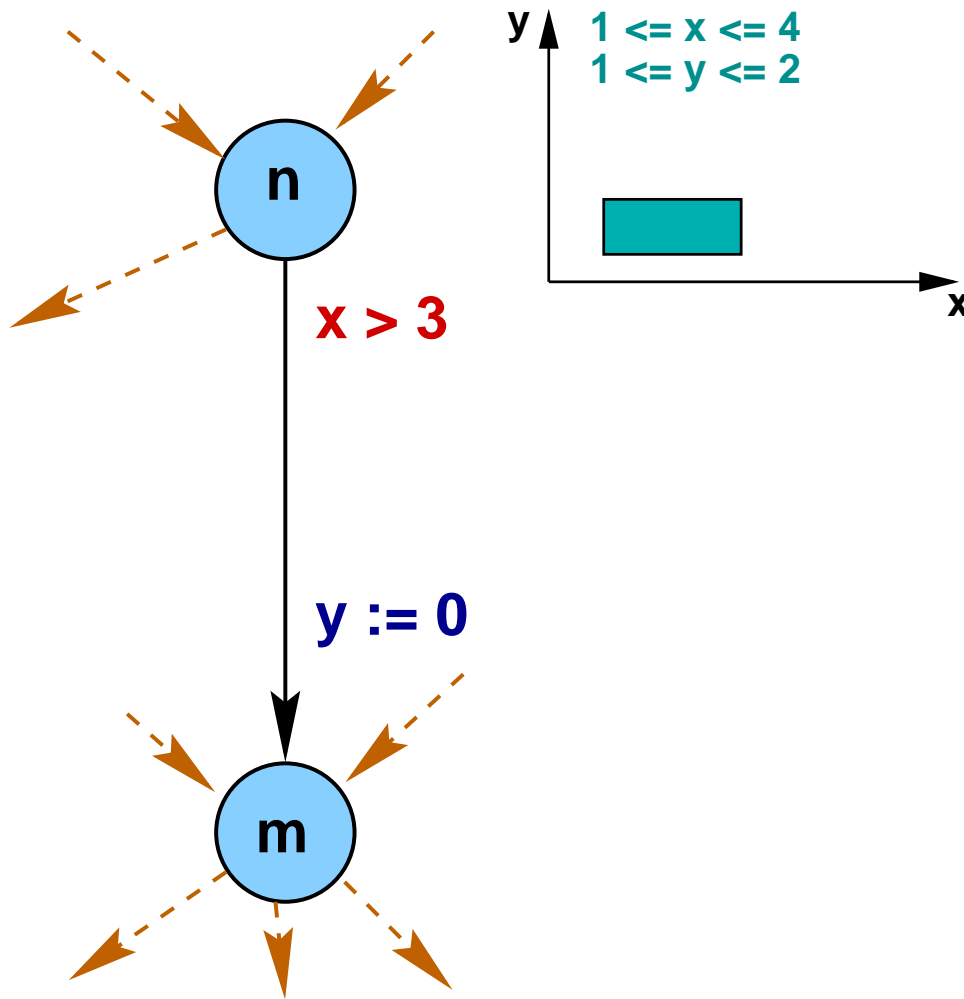
```
clock x; int count
```

- network of timed automata
- discrete data types
- arrays
- hand-shake synchronization
- urgency
- template mechanism
- committed locations
- **forward** state-space exploration

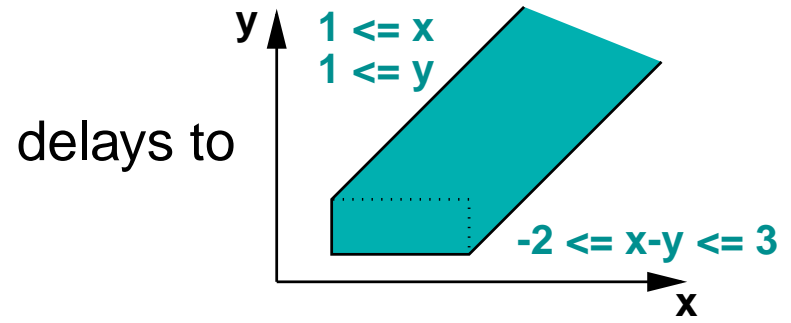
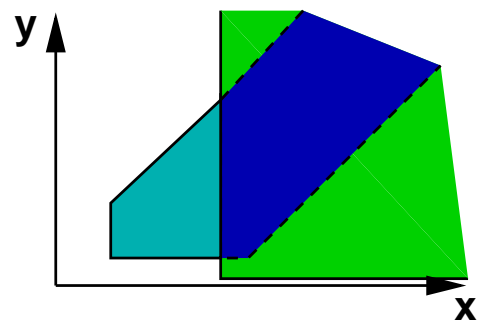
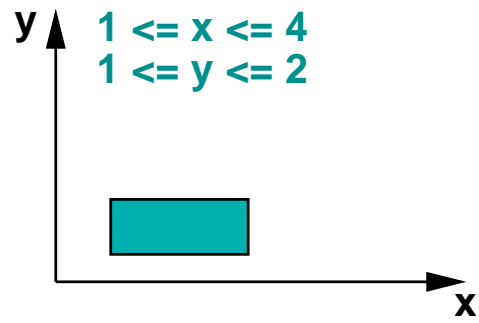
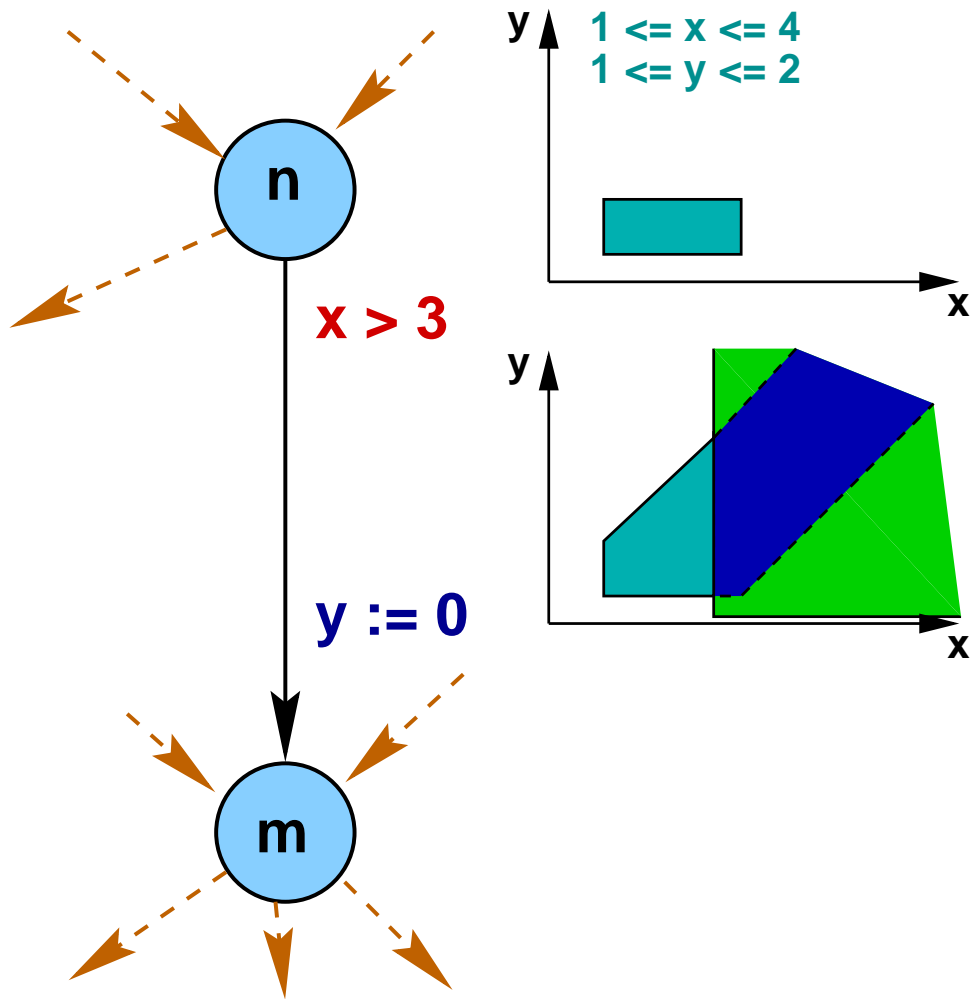
Symbolic Transitions



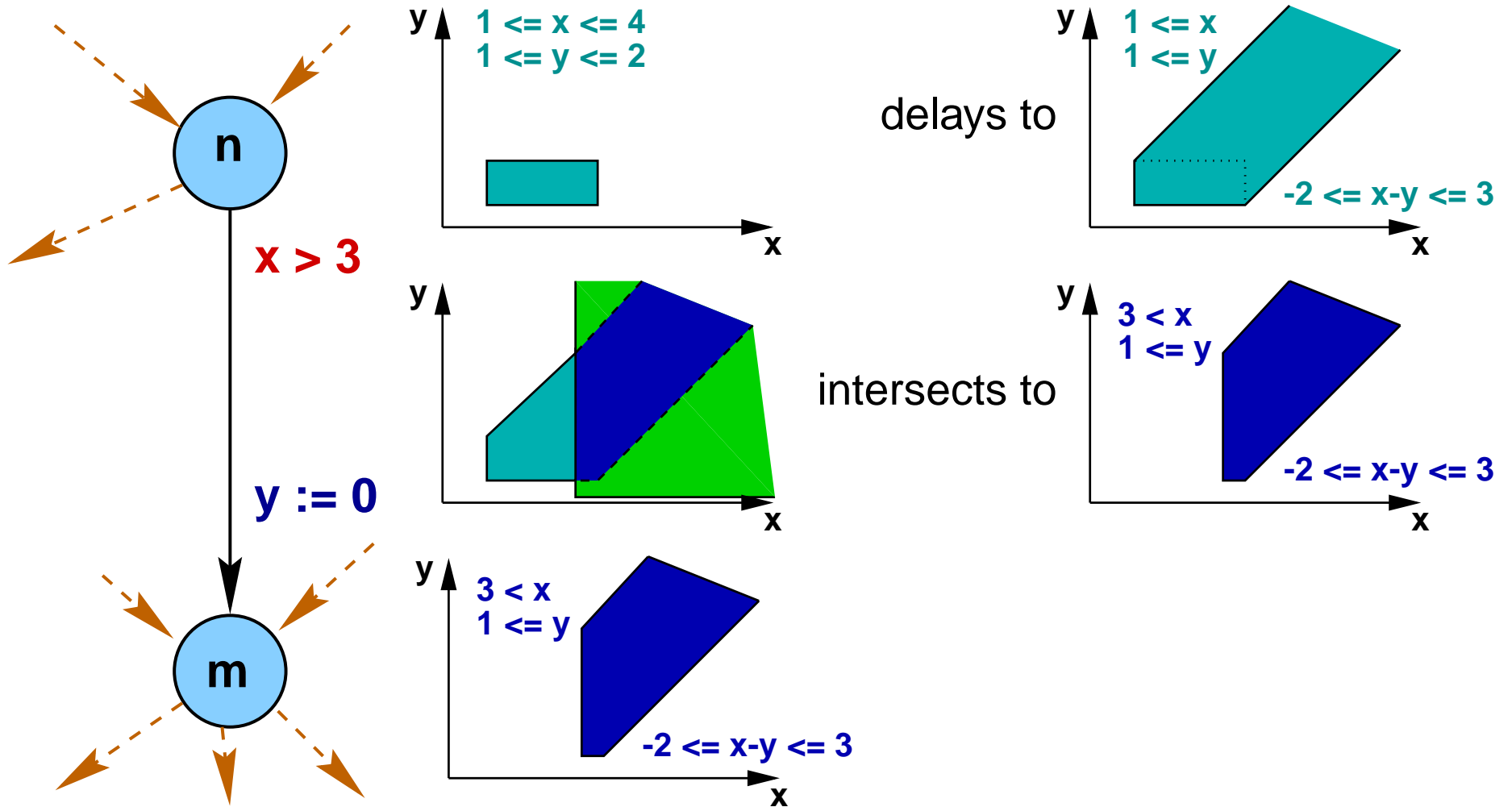
Symbolic Transitions



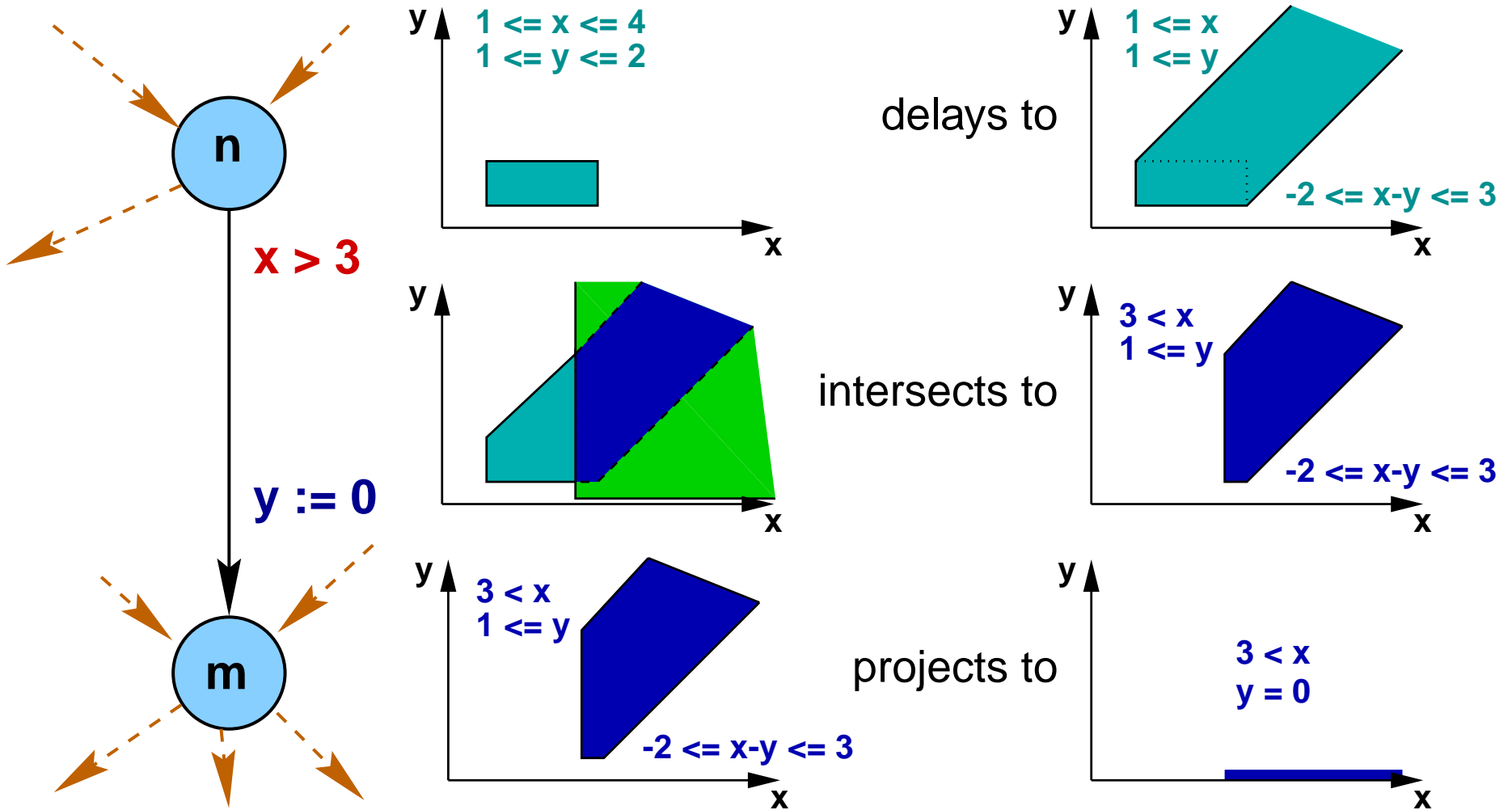
Symbolic Transitions



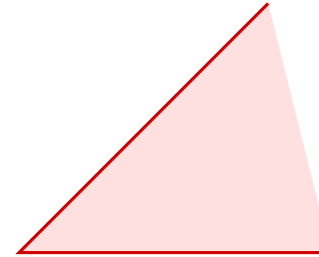
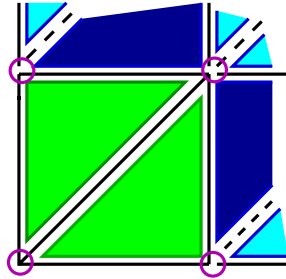
Symbolic Transitions



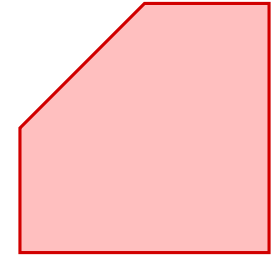
Symbolic Transitions



Sets of Clock-Evaluations



$$y - x \leq 0$$

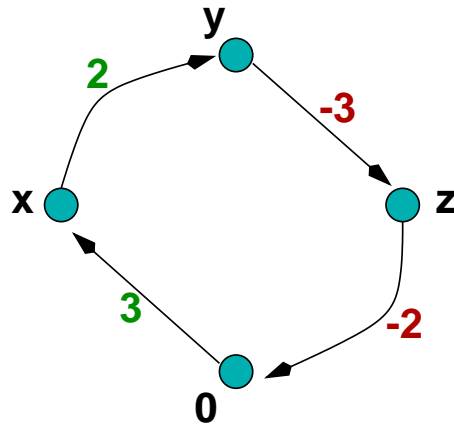


$$1 \leq x < 3 \wedge y \leq 2 \wedge y - x \leq 0$$

regions: smallest distinguishable sets

zones: convex unions of regions

representing (unions of) zones: DBMs, CDDs, DDDs, ...

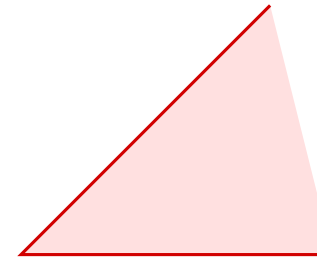
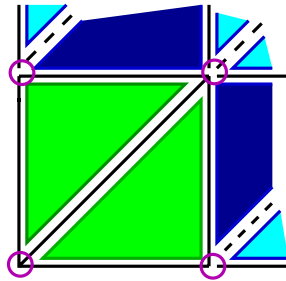


difference-bounded matrices

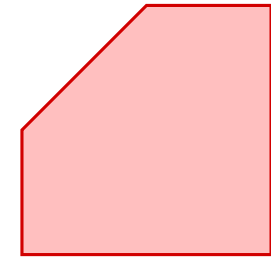
canonical

static

Sets of Clock-Evaluations



$$y - x \leq 0$$

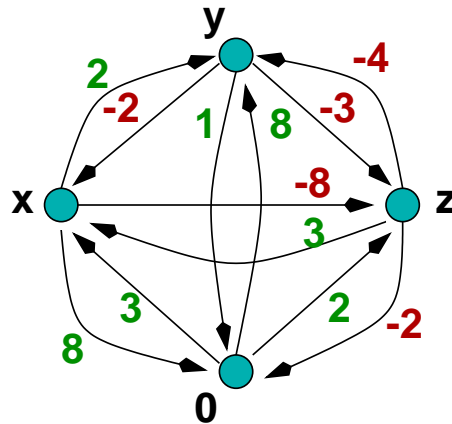


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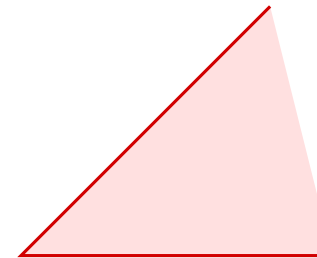
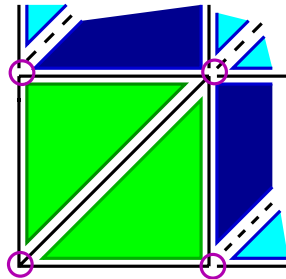


difference-bounded matrices

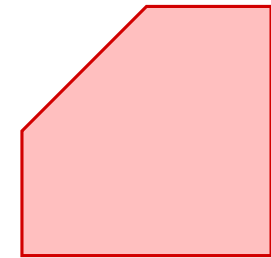
canonical

static

Sets of Clock-Evaluations



$$y - x \leq 0$$

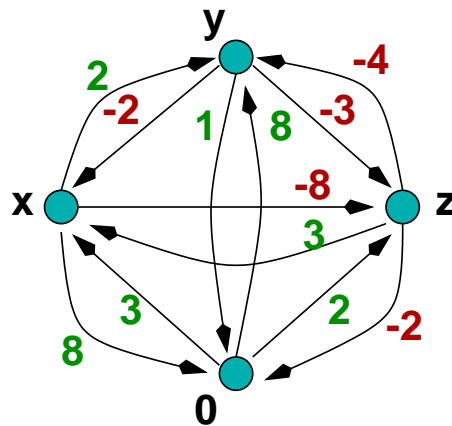


$$1 \leq x < 3 \wedge y \leq 2 \wedge y - x \leq 0$$

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zones: convex unions of regions

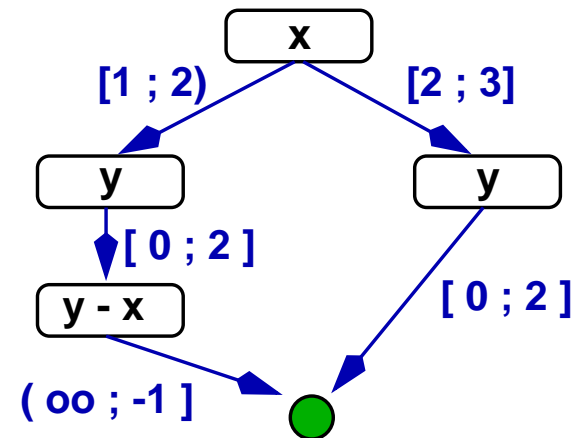
representing (unions of) zones: DBMs, CDDs, DDDs, ...



difference-bounded matrices

canonical

static

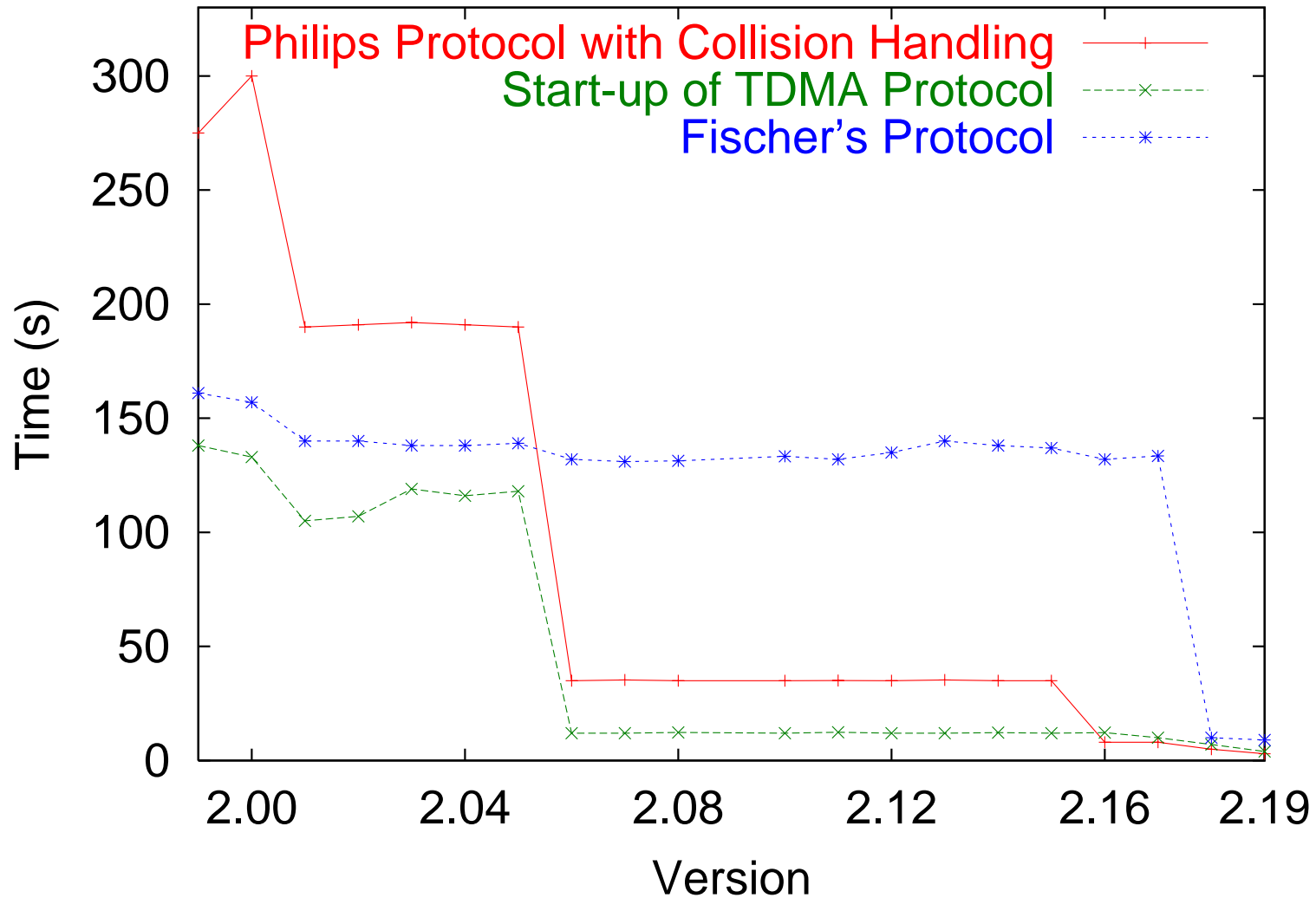


clock difference diagrams

non-canonical

flexible

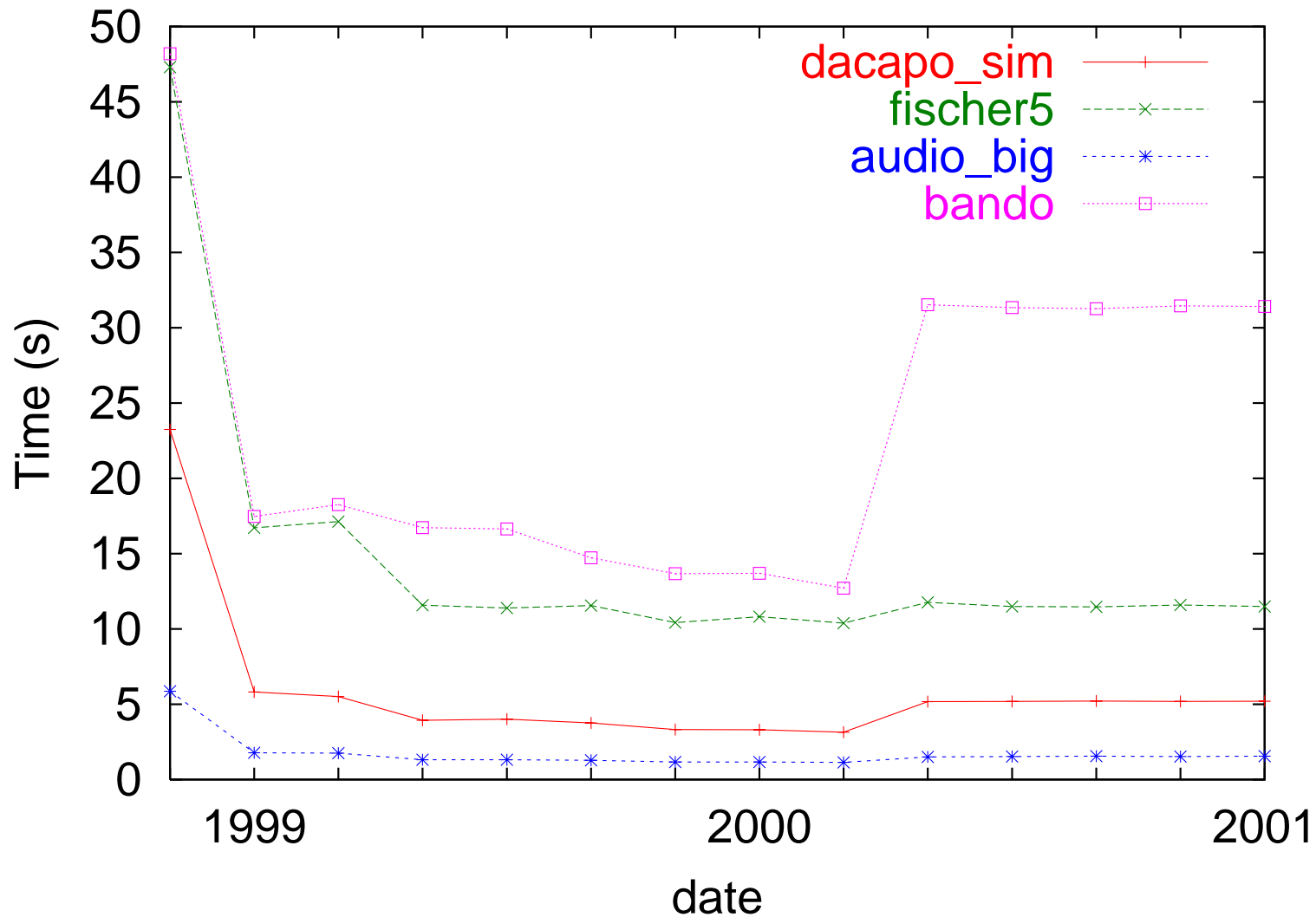
Engineering Improvements Dec '96 - Sept '98



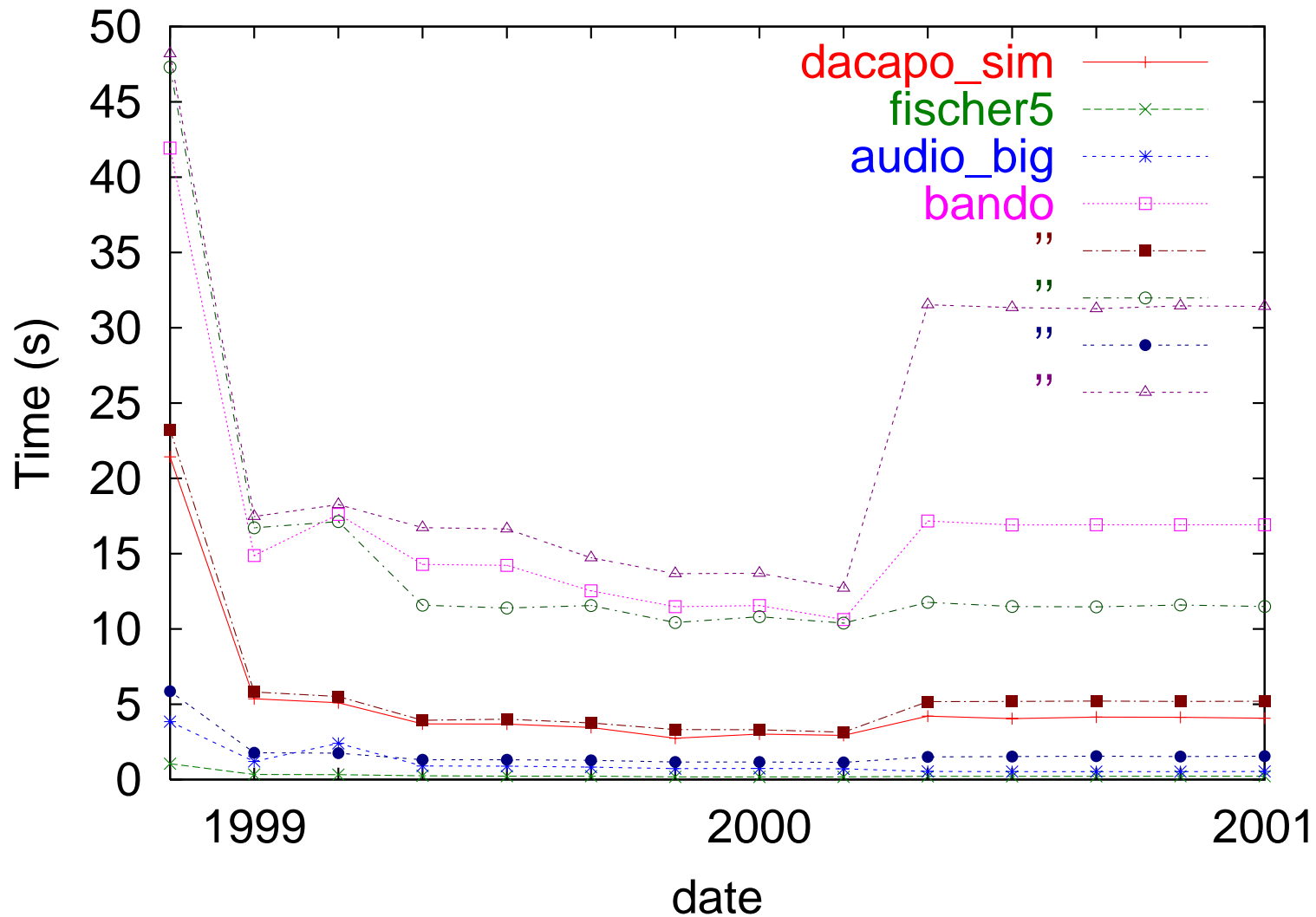
Internal Optimizations

- × committed locations (to reduce interleavings)
 - × active clock reduction
 - × variation of search order
 - × local reduction (compact DBM representation)
 - × global reduction (remove covered states from *Passed*)
 - ≈ convex hull over-approximation [safe]
 - ≈ bit-state hashing [sound]
- ... and of course: *a lot of software engineering!*

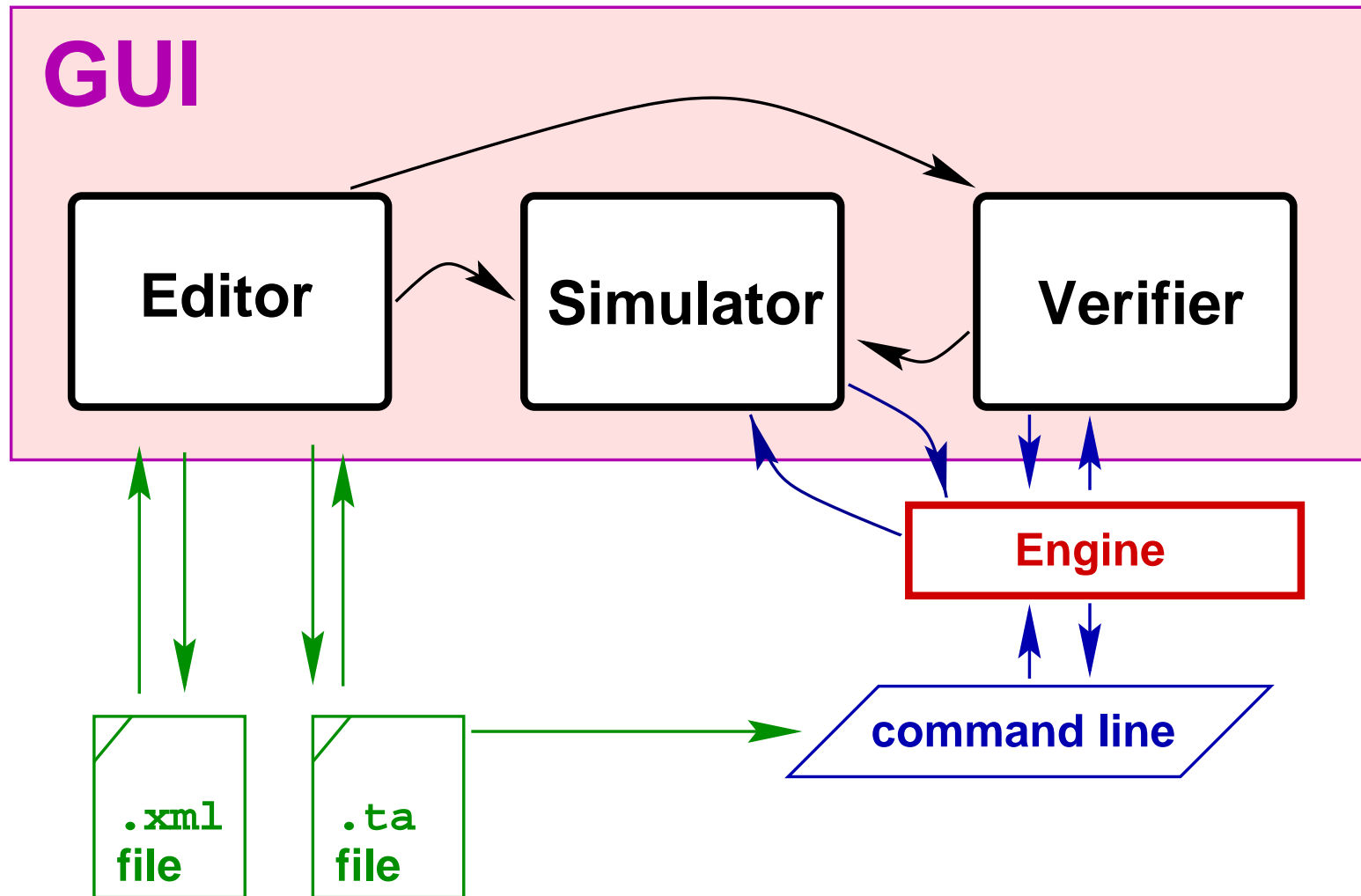
Benchmarks (without optimizations)



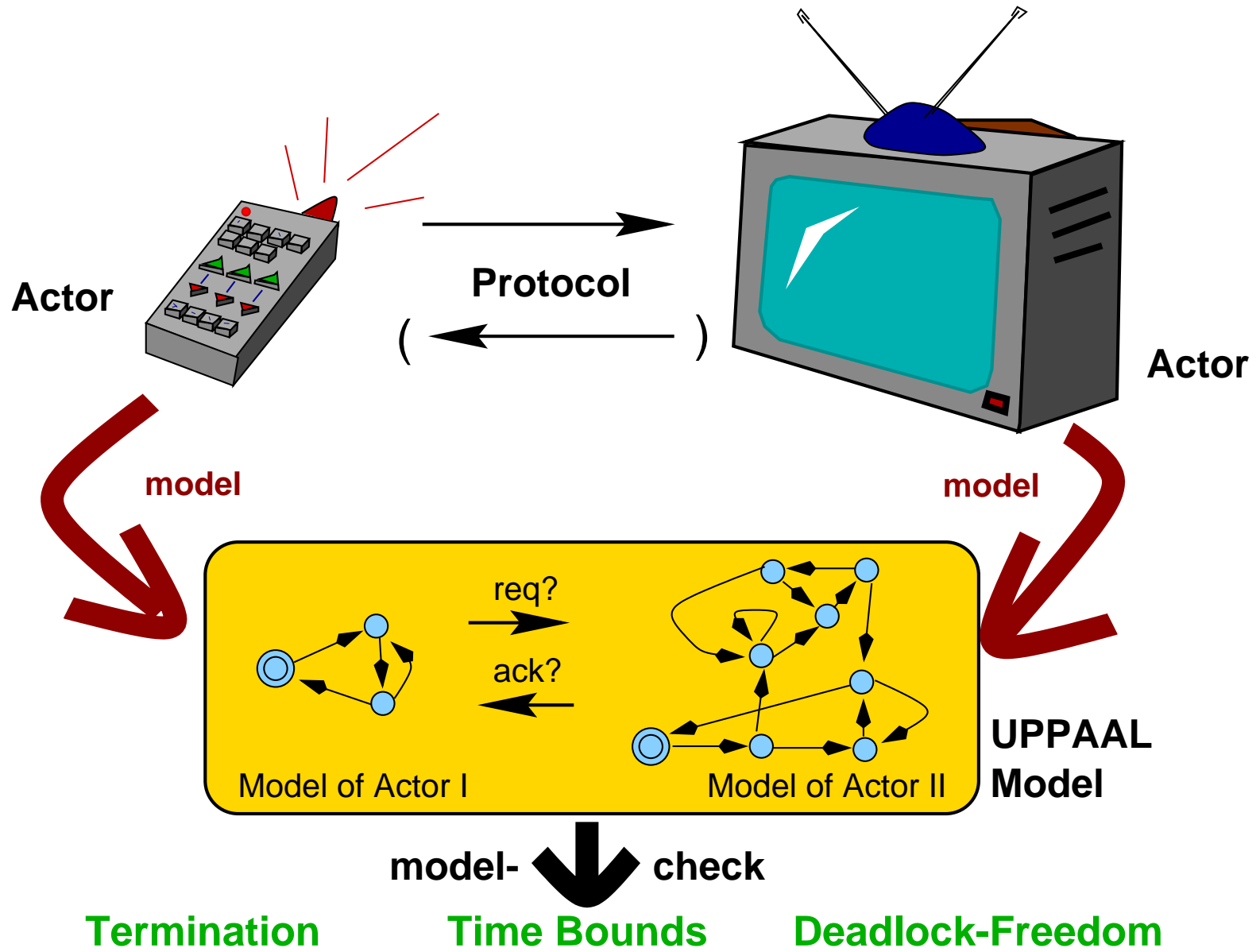
Benchmarks (with optimizations)



Architecture of UPPAAL



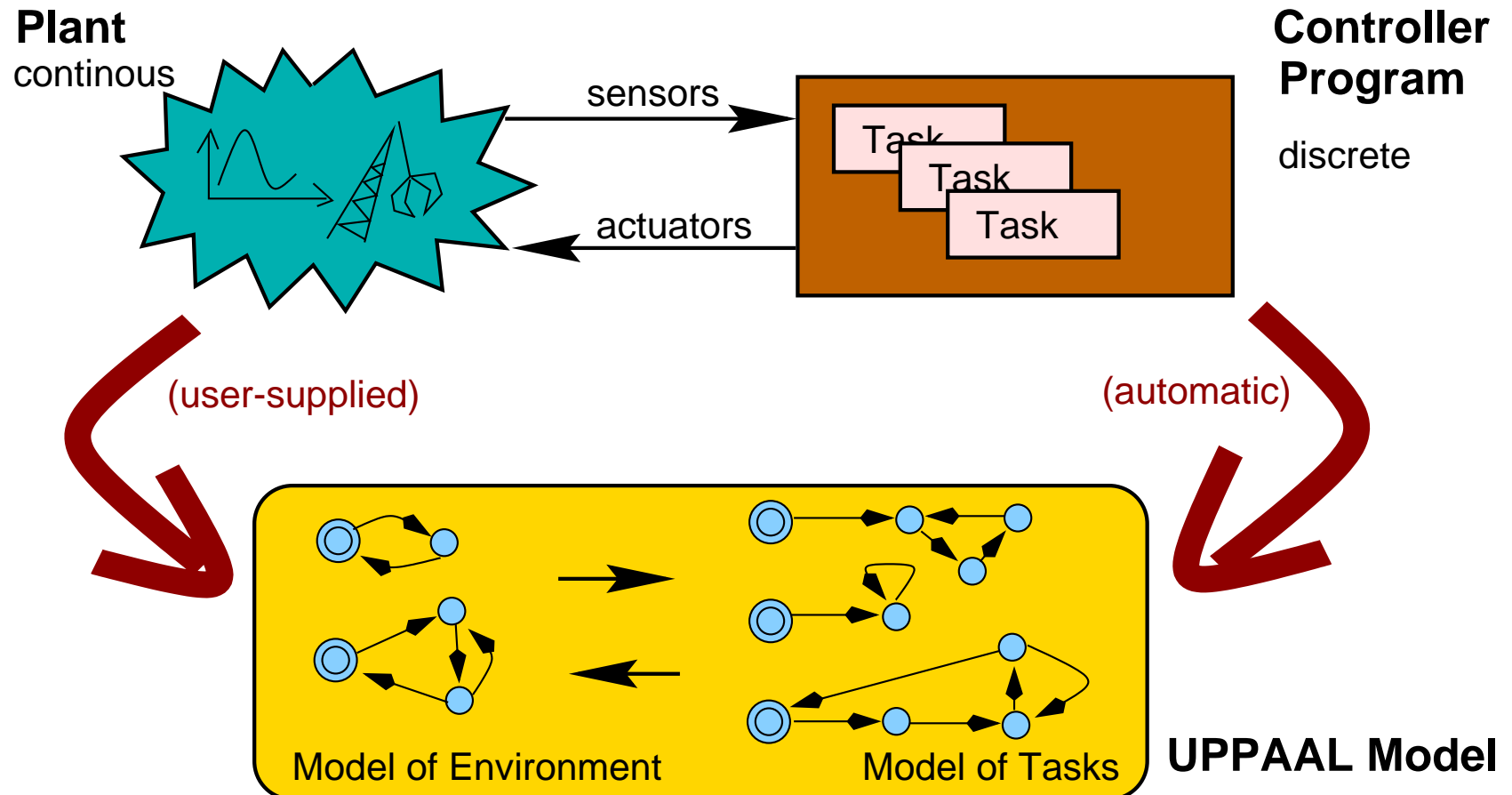
Communication Protocols



Case Studies: Protocols

- Philips Audio Protocol [HS95, CAV95, RTSS95, CAV96]
- Collision-Avoidance Protocol [SPIN95]
- Bounded Retransmission Protocol [TACAS97]
- Bang & Olufsen Audio/Video Protocol [RTSS97]
- TDMA Protocol [PRFSTS97]
- Lip-Synchronization Protocol [FMICS97]
- Multimedia Streams [DSVIS98]
- ATM ABR Protocol [CAV99]
- ABB Fieldbus Protocol [ECRTS2k]
- IEEE 1394 Firewire Root Contention [STTT'01]

Composing the Embedded System Model



Case Studies: Controllers

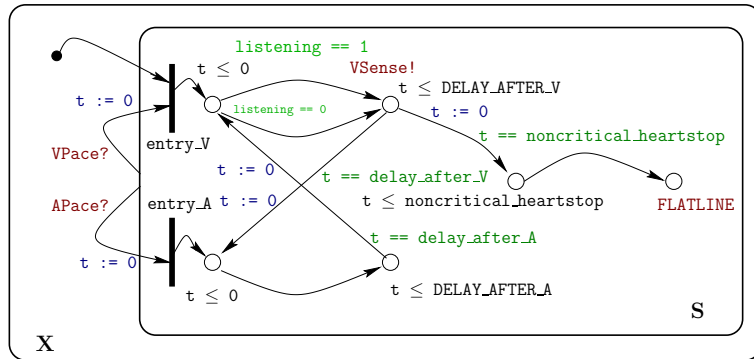
- Gearbox Controller [TACAS98]
- Bang & Olufsen Power Controller [RTPS99, FTFT2k]
- SIDMAR Steel Production Plant [RTCSA99, DSVV2k]
- Real-Time RCX Control-Programs [ECRTS2k]
- RCX Production Cell (2000)
- Experimental Batch Plant [ICDCS'01]
- Saab Car Locking System [RT-TOOLS'01]

Extensions of the Modeling Language

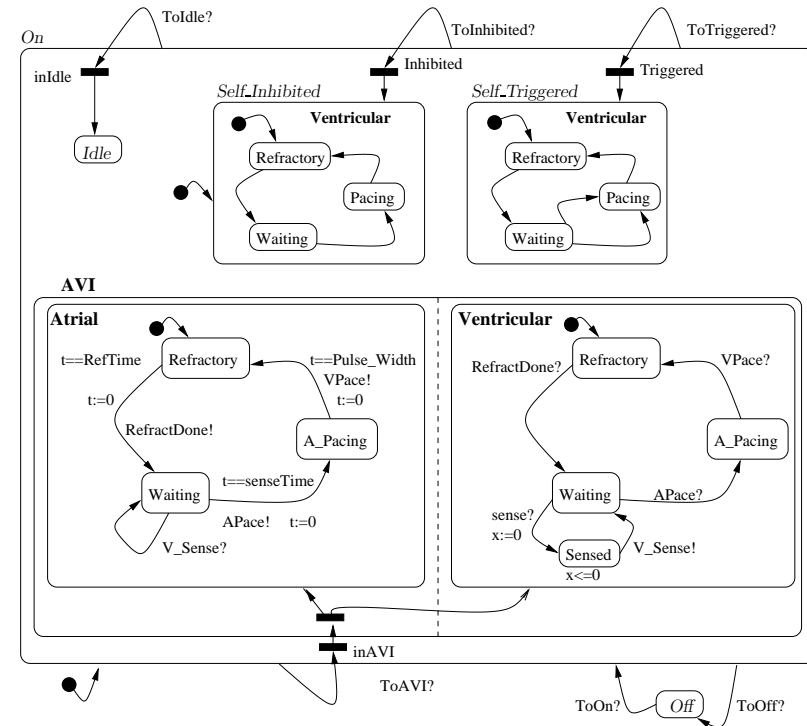
- ➔ **Stopwatch** extension
- ➔ **Probabilistic** timed automata
- ➔ **Hierarchical** timed automata
- ➔ **Parameters** on clock constraints
- ➔ **Cost-Optimal** timed automata
- ➔ **Executable** timed automata

Hierarchical UPPAAL

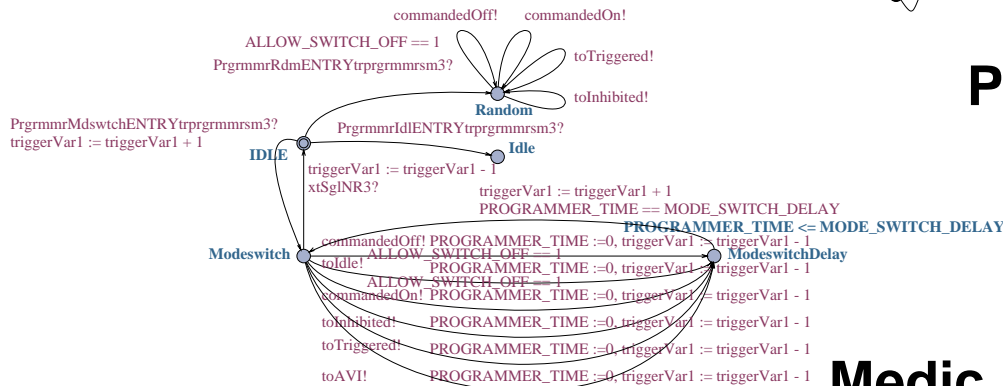
Use **hierarchical** timed automata:



Human Heart



Pacemaker



Medic

Flattened Version of the Pacemaker

HTA model	# XML tags	564	→	1191	UPPAAL model
	# proper control locations	35	→	45	

- SAFETY:

$A[] \neg \text{heart stops}$

- LIVENESS:

$A[] V\text{contract} \Rightarrow A\langle\rangle A\text{contract}$

Parameters:

REFRACTORY_TIME = 50

SENSE_TIMEOUT = 15

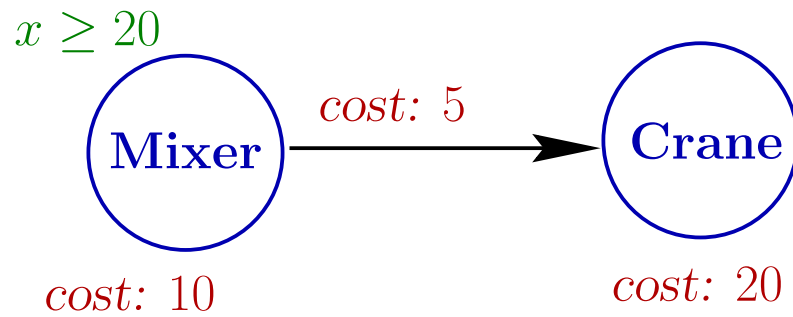
DELAY_AFTER_V = 50

DELAY_AFTER_A = 5

MODE_SWITCH_DELAY = 66

E.g. for $\text{MODE_SWITCH_DELAY} = 65$, $A[] \neg \text{heart stops}$ is violated

Cost-Optimality



Idea: Add *cost* to locations and actions

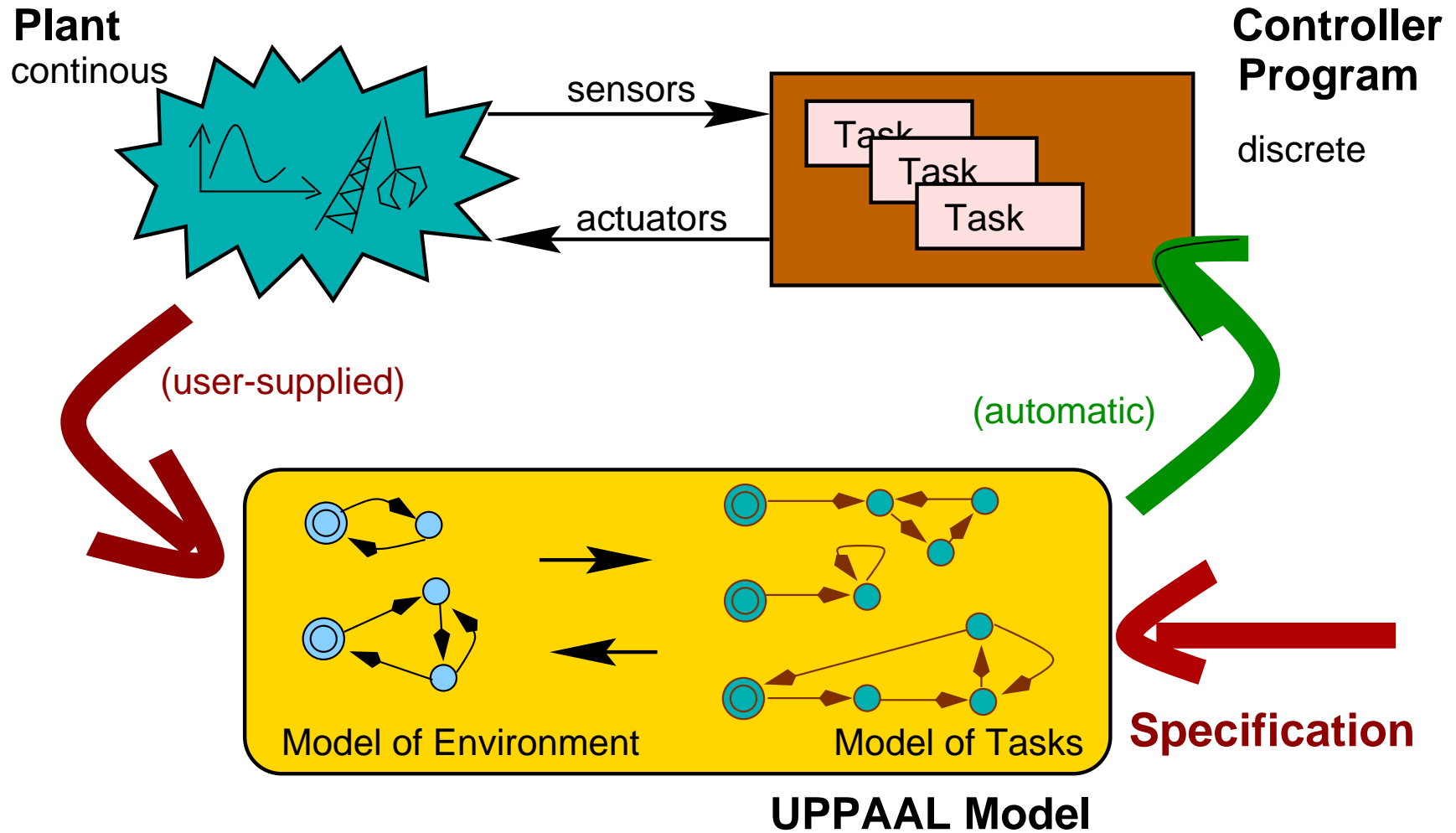
Starting Point: 'cost' not necessarily uniform

Approach: attach different (integer) prices to locations
treat algorithmically with *priced zones*

Applied: compute schedule for a steel batch plant in Gent
and a LEGO model of it [Feh99, HLP00]

Fact: Cost-Optimal trace is computable

Controller Synthesis



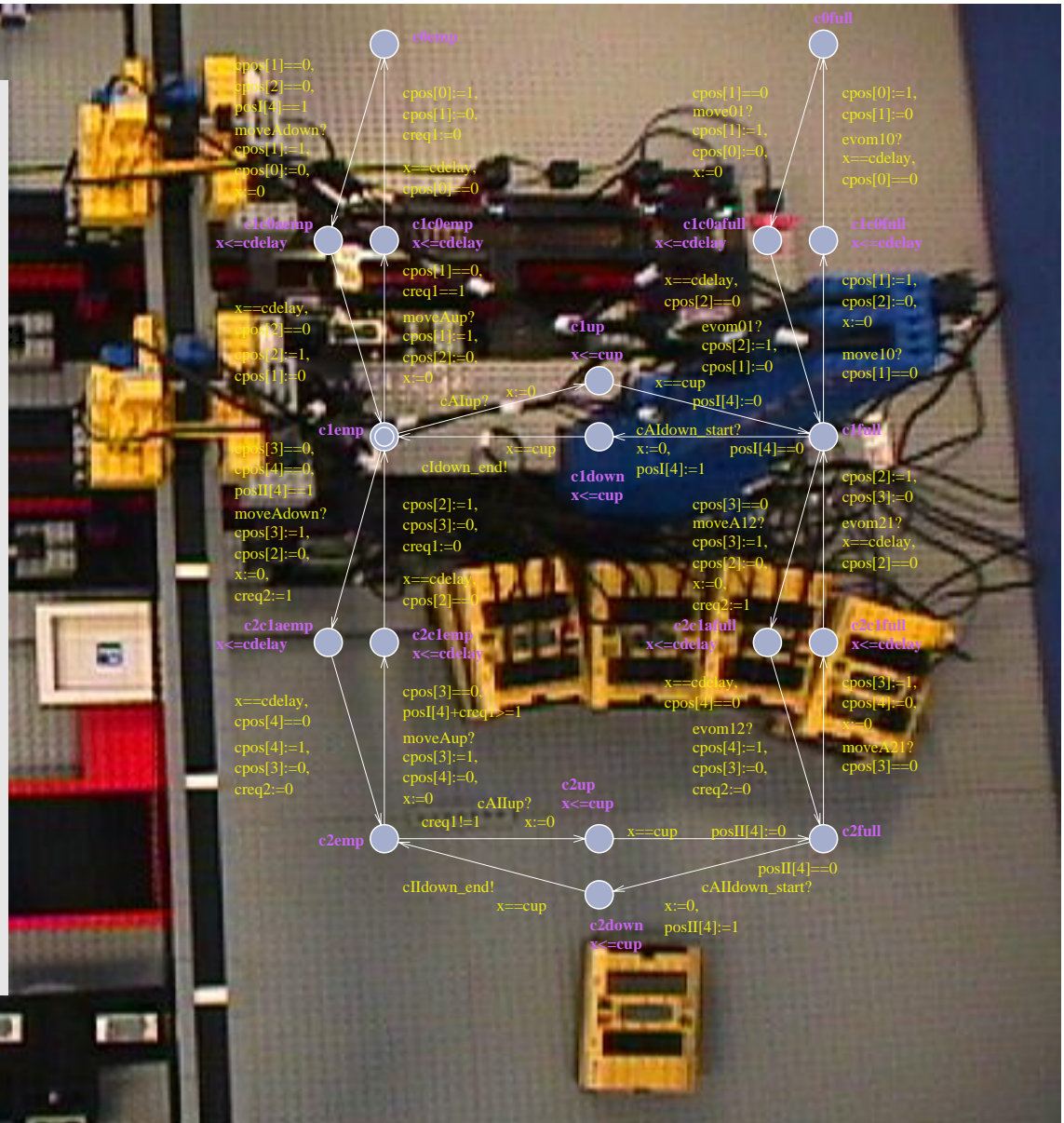
SIDMAR Steel Production Plant (LEGO Version)

```

'''Delay 15
PB.Wait 2, 1500

'''cAIup();
'''Crane A - Pick UP
PB.PlaySystemSound 1
PB.SendPBMMessage 2, 97 'Pick up, on
PB.SetVar 1, 15, 0 'Wait for ack
PB.While 0, 1, 3, 2, 97
PB.Wait 2, 20
PB.SetVar 1, 15, 0 'Read the message
PB.ClearPBMMessage
PB.SumVar 2, 2, 1
PB.If 0, 2, 2, 2, 20
'If looped 20 times
PB.PlaySystemSound 1
PB.SendPBMMessage 2, 97 'Then Send
'message, again same as sendig 0
PB.SetVar 2, 2, 0
PB.EndIf
PB.EndWhile

'''Delay 10
PB.Wait 2, 1000
    
```



Cost-Optimal Extension: Summary

- completely random schedules not analyzable
→ guides/optimality *restrict* behavior
- the LEGO model helped *debugging* the UPPAAL model

Compared to traditional (LP) methods:

- reasonably efficient
- more **flexible**
- *aircraft landing* case study:
computed schedules either **better** or **substantially worse**

Completed Parts

- ✓ cost-optimal extension
- ✓ parametric extension
- ✓ stopwatch extension
- ✓ distributed UPPAAL

Work in Progress

- probabilistic extension
- hierarchical extension
- executable UPPAAL

Work Planned

- ★ dynamic partitioning
- ★ hybrid animation

Go, Get It!

UPPAAL2k (3.2.1) available for

Linux, SunOS, and MS Windows

<http://www.uppaal.com/>

Since July 1999: > 1'000 downloads (from different users)

> 60 countries

Open mailing list: <http://groups.yahoo.com/group/uppaal>

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Science.

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- [SS01] D. Simons and M. Stoelinga. Mechanical verification of the ieee1394a root contention protocol using uppaal2k. 2001. To appear in International Journal on Software Tools for Technology Transfer.

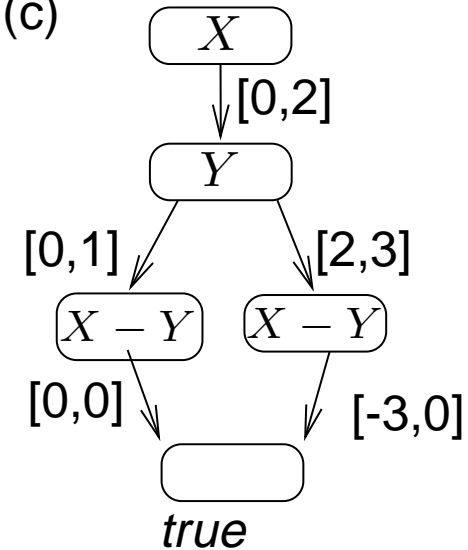
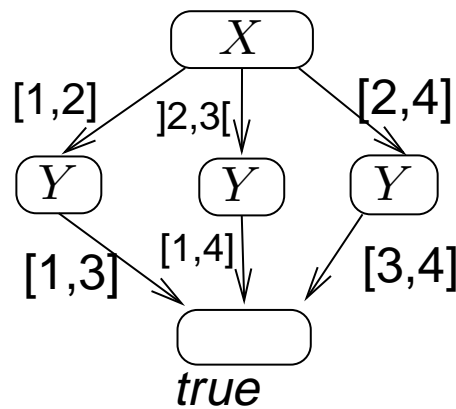
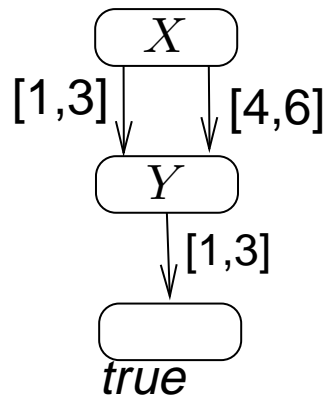
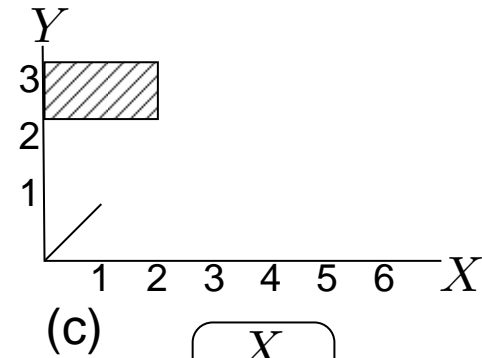
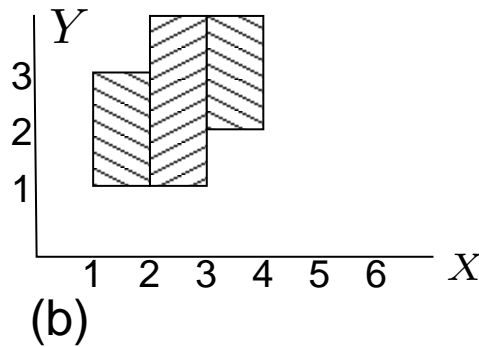
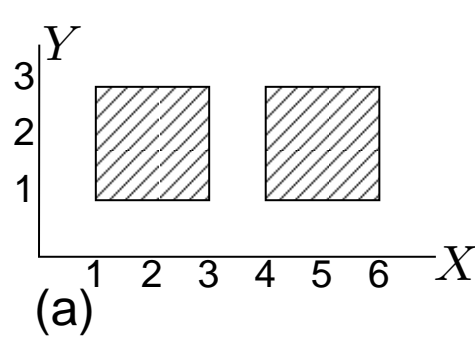
Clock Difference Diagrams (CDDs)

Data structure to express disjunction of zones

- similar to BDDs
- rooted, directed, acyclic graph
- every node labeled x or $x - y$
- every edge labeled with an interval
- order of labels fixed
- one terminal node: true
- missing edges lead to false

 *not canonical*

Clock Difference Diagrams (CDDs) (2)



Stopwatch UPPAAL

timed automaton + stopwatches = SWA

Fact: Any *timed language* accepted by a *linear hybrid automaton* can also be accepted by a *stopwatch automaton*

linear hybrid automaton *—translate→* **SWA**

Problem: reachability analysis of SWA is undecidable

Observation: often it suffices to *over-approximate* reachability

Approach: run DBM-based SWA, with *approximative future*
(only differences of *two* stop-watches considered)

Notes: way to *translate* effects accuracy
more sophisticated translations could preserve *termination*

Probabilistic UPPAAL

Example Problem:

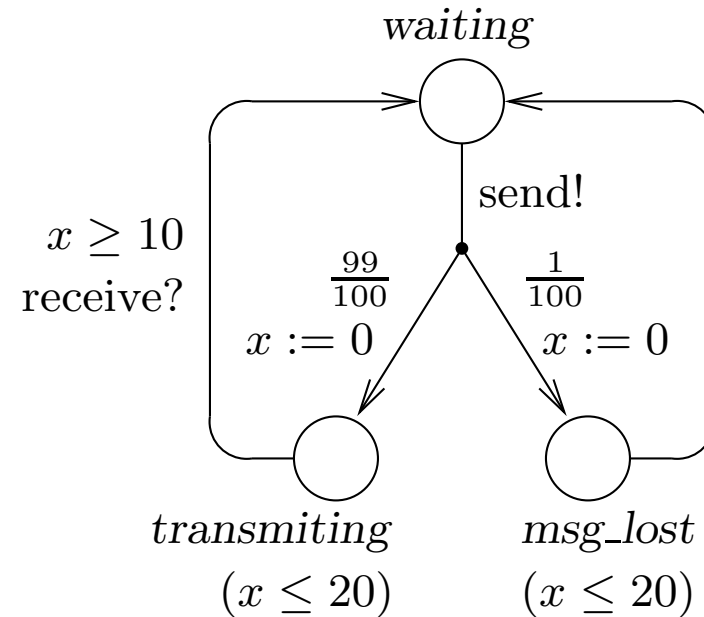
Lossy channel with known probabilities

Cannot prove:

in time X , message will arrive

But:

$P_{\geq 95\%}(\forall \square_{\leq 1000} \text{received})$



existing Approaches: Jensen 96, Kwiatkowska et al. 99

Problem: based on region graph construction

new Approach: use minimization techniques to obtain

stable probabilistic zone graphs

use matching data structure

Determining Parameters: *Parametric-Uppaal*

Parameters: in clock guards $x \bowtie p, x - y \bowtie p$
 $\bowtie \in \{<, \leq, =, \geq, >\}, p$ a linear expression

Fact: parameterized timed reachability undecidable for systems with ≥ 3 clocks [AHV93]

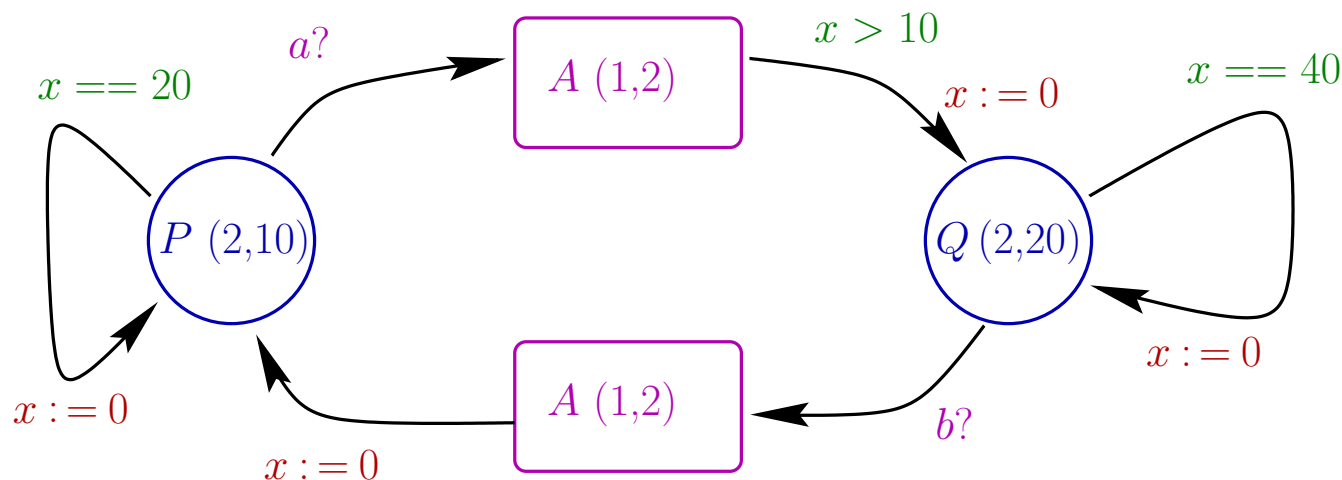
UPPAAL + LP solver (from PMC tool) = *semi-algorithm*

data-structure: parametric DBMs

modified algorithm: split, if the outcome of a comparison is dependent on parameter values

not guaranteed to terminate \Rightarrow output partial solutions

Executable Timed Automata



Periodic Tasks P, Q

Spontaneous Tasks A, B

Parameters: **worst-case execution time**, **deadline**

Delay transition \equiv execute task with earliest deadline

Action transition \equiv releases a new task

Automaton schedulable \Leftrightarrow every $a!, b!$ -sequence schedulable

Fact: added *Preemption* is as expressive as TAs with stop watches

UPPAAL in the European WOODDES project

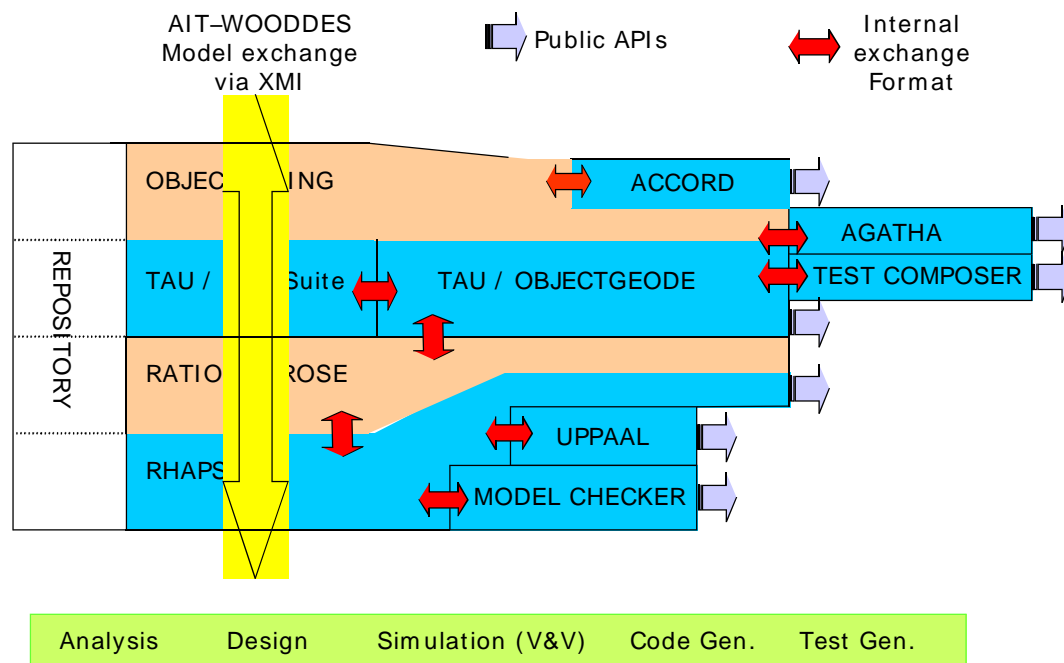
Workshop for Object-Oriented Design and Development of Embedded Systems

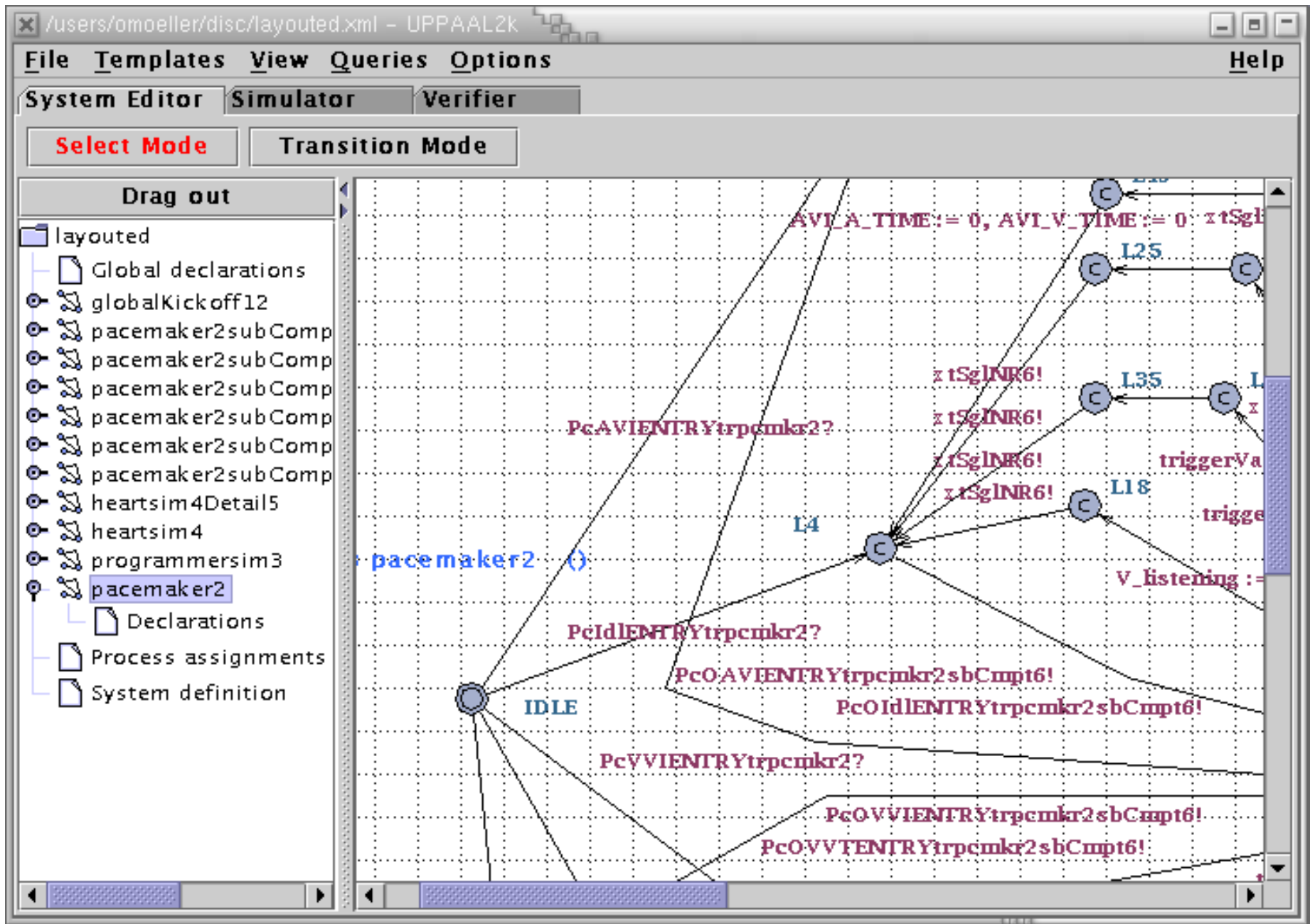
Partners:

-  PSA
-  Mecel
-  CEA
-  SOFTEAM
-  I-Logix
-  Intracom
-  Offis
-  Uppsala
-  Aalborg

Objectives:

- UML Real-Time profile
- WOODDES methodology & tool platform





/users/omoeller/disc/layouted.xml - UPPAAL2k
 File Templates View Queries Options Help
 System Editor Simulator Verifier

Drag out

Enabled Transitions

(pacemaker2subComponent6AVIMode9.1, ...)

Next Reset

Simulation Trace

(heartsim4.2, heartsim4Detail5.1)
 (Detail, AContraction, Modeswitch, L7, ID...
 (pacemaker2.5, pacemaker2subCompon...
 (Detail, AContraction, Modeswitch, subC...
 (pacemaker2subComponent6.3, pacema...
 (Detail, AContraction, Modeswitch, subC...
 (pacemaker2subComponent6AVIMode9.2...
 (Detail, AContraction, Modeswitch, subC...
 (pacemaker2subComponent6AVIMode9.1...
 (Detail, AContraction, Modeswitch, subC...

Trace File: _____

Prev Next Replay
 Open Save Random

Slow Fast

Drag out

Variables

wasSwitchedC
 V_listening =
 A_LISTENING_
 triggerVar1 =
 triggerVar2 =
 triggerVar3 =
 triggerVar4 =
 triggerVar5 =
 triggerVar7 =
 VVI_TIME = 0
 VVT_TIME = 0
 AVI_A_TIME =
 AVI_V_TIME =
 HEART_TIME =
 PROGRAMMER
 VVT_TIME = V
 AVI_A_TIME =
 AVI_V_TIME =
 HEART_TIME =
 PROGRAMMER
 AVI_A_TIME =
 AVI_V_TIME =
 HEART_TIME =
 PROGRAMMER
 HEART_TIME =
 PROGRAMMER
 HEART_TIME =
 PROGRAMMER

L57
 x tSgINR9!
 triggerVar7 := triggerVar7 - 1
 x tSgINR11?
 IMd9VPrt11?
 IDLE
 r7 := triggerVar7 - 1
 x tSgINR11?
 Refractory
 AVI_A_Pace_Done
 AVI_Refracto
 V_listening :=
 Ventr
 AVI_
 x tSgINR11?
 triggerVar7 := triggerVar7 - 1

