

BRICS Qualifying Exam

Automation for Formal Verification: Exploiting Structure

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Roadmap

Part I Automation in theorem proving: congruence closure

Part II Automation in model checking: hierarchical decomposition

Part III Automation in concurrency: identifying togetherness

Roadmap

Part I Automation in theorem proving: congruence closure

- ★ congruence closure framework
- ★ bit-vector theories
- ★ computational complexity of solving

Part II Automation in model checking: hierarchical decomposition

Part III Automation in concurrency: identifying togetherness

Automated Theorem Proving

$$\Gamma \vdash \varphi$$

Γ : assumptions

φ : conclusion

Inference system \rightsquigarrow Theorem prover

We want *reasonable* tool support:

- high-level strategies (like *induct* & *simplify*)
- heuristics to search for proofs
- full automation in simple cases

Automated Theorem Proving

$$\Gamma \vdash \varphi$$

Γ : assumptions

φ : conclusion

Inference system



Theorem prover

sequent calculus

PVS

We want *reasonable* tool support:

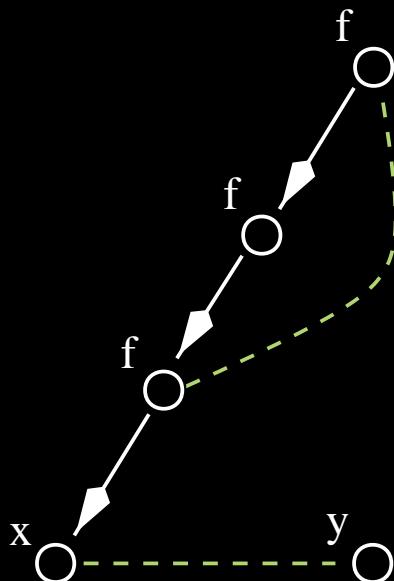
- high-level strategies (like *induct* & *simplify*) ✓
- heuristics to search for proofs ✓
- full automation in simple cases congruence closure

Encoding Equations in a DAG

Given: $fff x = f x, \quad x = y$

Conclude: $fffff y = f x$

as a
graph

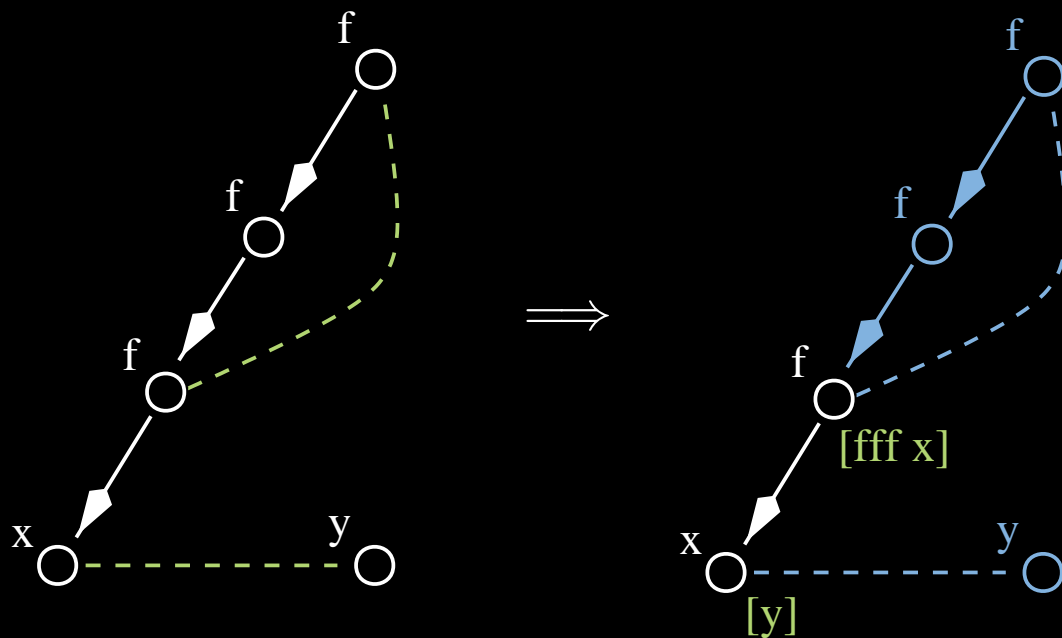


Encoding Equations in a DAG

Given: $fff x = f x, \quad x = y$

Conclude: $fffff y = f x$

as a
graph



cut
out
redundant
parts

$$\begin{aligned}
 fffff y &= fffff x \\
 fffff x &= fff x \\
 fff x &= f x
 \end{aligned}$$

Shostak Style Framework

Theorem

$$T \vdash a = b \quad \text{iff} \quad \text{node}(a) \hat{R}_T \text{node}(b)$$

Shostak '84: It is possible to combine *several* theories in this framework, if they are *algebraically solvable*.

For every theory we have

canonizer: term $t \longrightarrow \sigma(t)$

unique representation: $\models t = u \Leftrightarrow \sigma(t) \doteq \sigma(u)$

solver: equation $t = u \longrightarrow \bigwedge_i x_i = s_i$

explicit description of all solutions

Bit-Vector Theories

Core

- $x_{[n]} : bvec_n$
number of bits n a constant
- Constants $c_{[n]}$, $c \in \mathcal{N}$
- Concatenation:

$$\begin{array}{ccc} \begin{array}{|c|c|c|} \hline \square & \square & \square \\ \hline \end{array} \otimes \begin{array}{|c|c|c|c|c|c|} \hline \square & \square & \square & \square & \square & \square \\ \hline \end{array} & \rightarrow & \begin{array}{|c|c|c|c|c|c|} \hline \square & \square & \square & \square & \square & \square \\ \hline \end{array} \\ x_{[3]} & & y_{[3]} & & x_{[3]} \otimes y_{[3]} \end{array}$$

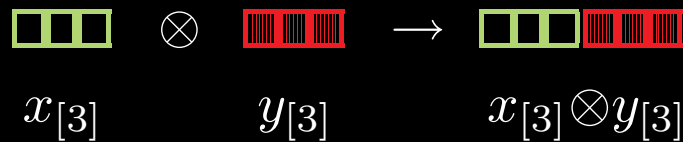
- Extraction:

$$\begin{array}{ccc} \begin{array}{|c|c|c|} \hline \square & \square & \square \\ \hline \end{array} [0 : 1] & \rightarrow & \begin{array}{|c|c|} \hline \square & \square \\ \hline \end{array} \\ x_{[3]} & & x_{[3]}[0 : 1] \end{array}$$

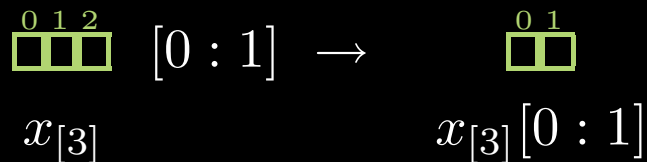
Bit-Vector Theories

Core

- $x_{[n]} : bvec_n$
number of bits n a constant
- Constants $c_{[n]}$, $c \in \mathcal{IN}$
- Concatenation:



- Extraction:



Extensions

- Boolean operations
- Arithmetic (modulo 2^n)

$$x_{[3]} \wedge y_{[3]}$$

$$x_{[3]} +_{[3]} y_{[3]}$$

- Variable length

$$x_{[n]} : bvec_n$$

$$n : \mathcal{IN}$$

- Variable Extraction

$$x_{[3]} [i:j] : bvec_{j-i+1}$$

$$i, j : \mathcal{IN}$$

Canonizing Bit-Vector Terms

Phase α : flatten extractions

$$\begin{array}{ccc}
 \begin{array}{c} 0 \ 1 \ 2 \\ \boxed{} \boxed{} \boxed{} \end{array} & \begin{array}{c} 0 \ 1 \ 2 \\ \boxed{} \boxed{} \boxed{} \end{array} & \\
 \left(x_{[3]} \otimes y_{[3]} \right) [0 : 3] & \rightsquigarrow & \begin{array}{c} 0 \ 1 \ 2 \\ \boxed{} \boxed{} \boxed{} \end{array} \begin{array}{c} 0 \\ \boxed{} \end{array} \\
 & & x_{[3]} \otimes y_{[3]} [0 : 0]
 \end{array}$$

Phase β : glue together

$$\begin{array}{ccc}
 \begin{array}{c} 0 \ 1 \\ \boxed{} \boxed{} \end{array} & \begin{array}{c} 2 \\ \boxed{} \end{array} & \\
 x_{[3]} [0 : 1] \otimes x_{[3]} [2 : 2] & \rightsquigarrow & \begin{array}{c} 0 \ 1 \ 2 \\ \boxed{} \boxed{} \boxed{} \end{array} \\
 & & x_{[3]}
 \end{array}$$

Bit-Vector Solver: Chop

$$(1) \quad p_{[n]} \otimes t = q_{[n]} \otimes u \quad \left\{ \begin{array}{l} p_{[n]} = q_{[n]} \\ t = u \end{array} \right\}$$

$$(1') \quad p_{[n]} \otimes t = q_{[m]} \otimes u, \quad n < m \quad \left\{ \begin{array}{l} p_{[n]} = \sigma(q_{[m]}[0 : n - 1]) \\ \sigma(q_{[m]}[n : m - 1]) \otimes u = t \\ q_{[m]} = \sigma(q_{[m]}[0 : n - 1]) \otimes \sigma(q_{[m]}[n : m - 1]) \end{array} \right\}$$

$$(1'') \quad p_{[n]} \otimes t = q_{[m]} \quad \left\{ \begin{array}{l} p_{[n]} = \sigma(q_{[m]}[0 : n - 1]) \\ \sigma(q_{[m]}[n : m - 1]) = t \\ q_{[m]} = \sigma(q_{[m]}[0 : n - 1]) \otimes \sigma(q_{[m]}[n : m - 1]) \end{array} \right\}$$

Bit-Vector Solver: Propagate

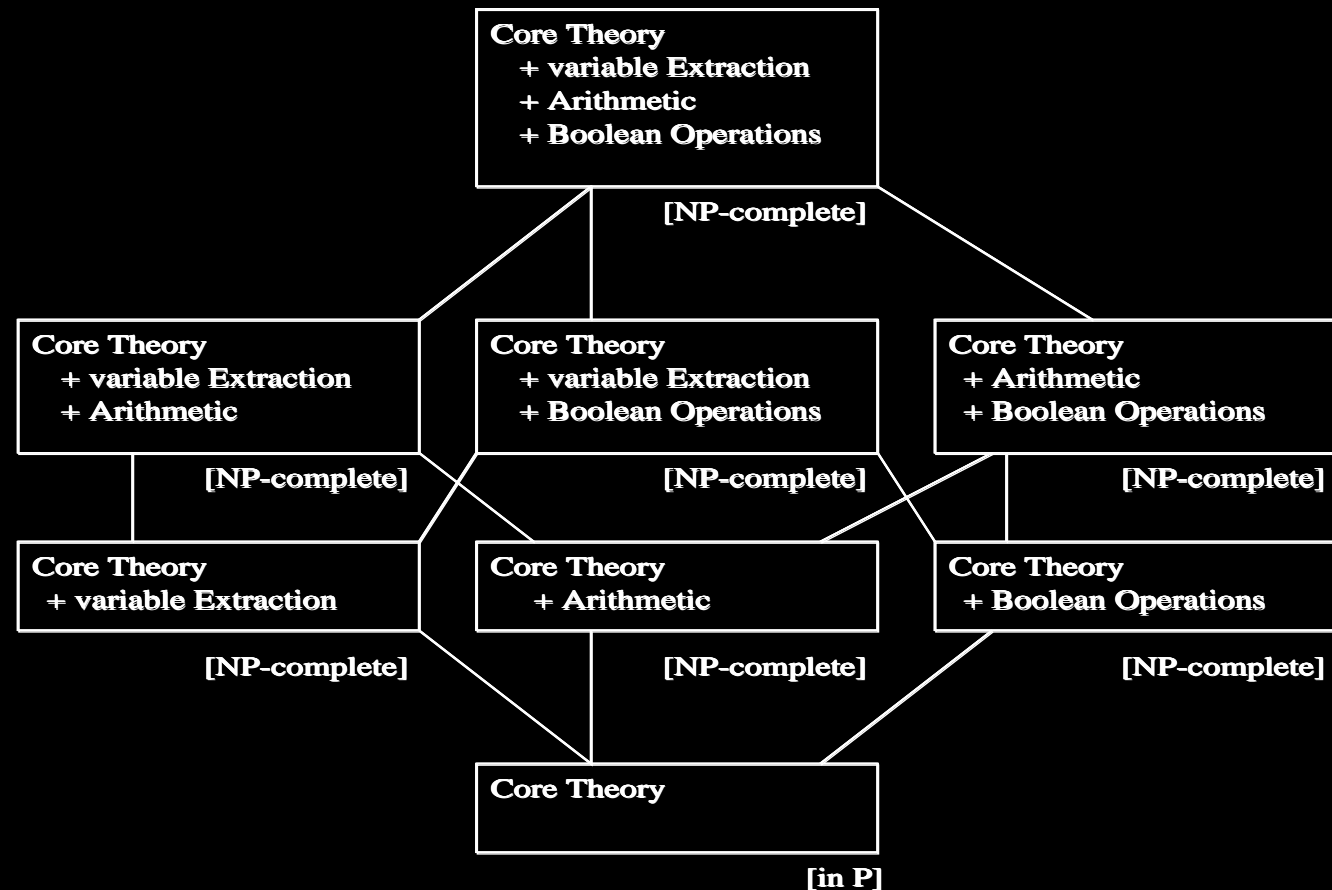
(2)	$c = d$,	$c \neq d$	FAIL
(3)	$t = t$		$\{\}$
(4)	$\left\{ \begin{array}{l} p = t \\ q = u \end{array} \right\}$,	$q \preceq t$	$\left\{ \begin{array}{l} p = t[q/u] \\ q = u \end{array} \right\}$
(5)	$\left\{ \begin{array}{l} p = q \\ q = r \end{array} \right\}$		$\left\{ \begin{array}{l} p = r \\ q = r \end{array} \right\}$
(6)	$\left\{ \begin{array}{l} p = q \\ q = p \end{array} \right\}$		$\{ p = q \}$
(7)	$\left\{ \begin{array}{l} p = t \\ p = u \end{array} \right\}$		$\left\{ \begin{array}{l} p = t \\ u = t \end{array} \right\}$
(8)	$c = t$,	$t \notin \mathcal{C}$	$\{ t = c \}$
(9)	$p = q \otimes t$,	$p \neq \sigma(q \otimes t)$	$\{ q \otimes t = p \}$

Complexity of the Satisfiability Problem

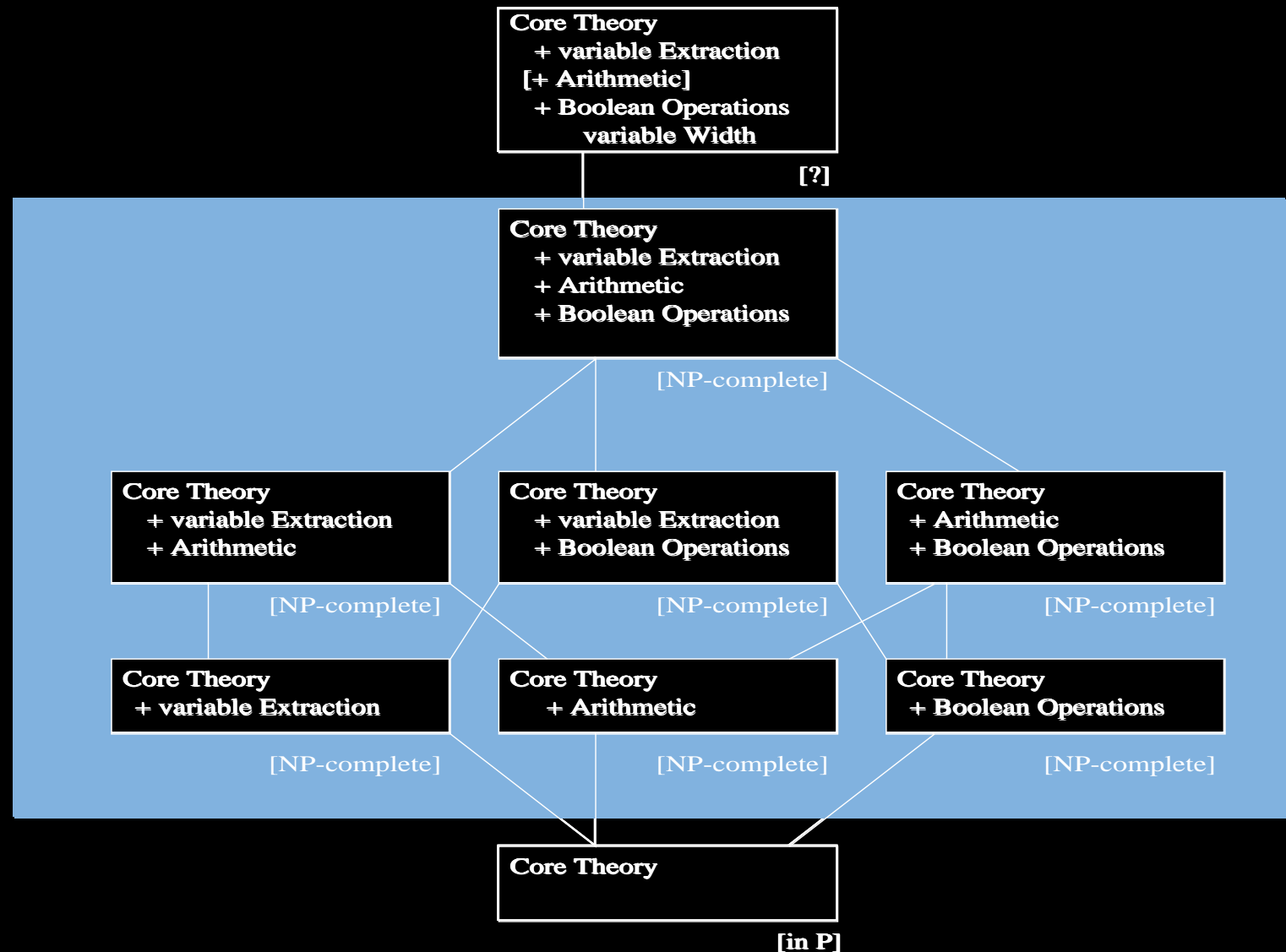
Core Theory

[in P]

Complexity of the Satisfiability Problem



Complexity of the Satisfiability Problem



Expressiveness of Solving

$$\forall x.\exists y.\exists z.(x \vee y) \leftrightarrow \neg z$$

$$\text{solve}((x \vee y) \leftrightarrow \neg z) = \left\{ \begin{array}{l} x = a \\ y = b \\ z = \neg a \wedge \neg b \end{array} \right\}$$

$$\forall x.\exists y.\exists z.(x \vee y) \leftrightarrow \neg z \quad : \text{true}$$

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$$\forall x.\forall y.\forall z.(x \vee y) \leftrightarrow \neg z \quad : \text{false}$$

$$\exists x.\forall y.\forall z.(x \vee y) \leftrightarrow \neg z \quad : \text{false}$$

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$$\exists x.\exists y.\exists z.(x \vee y) \leftrightarrow \neg z \quad : \text{true}$$

Quantification Lemma

General Method

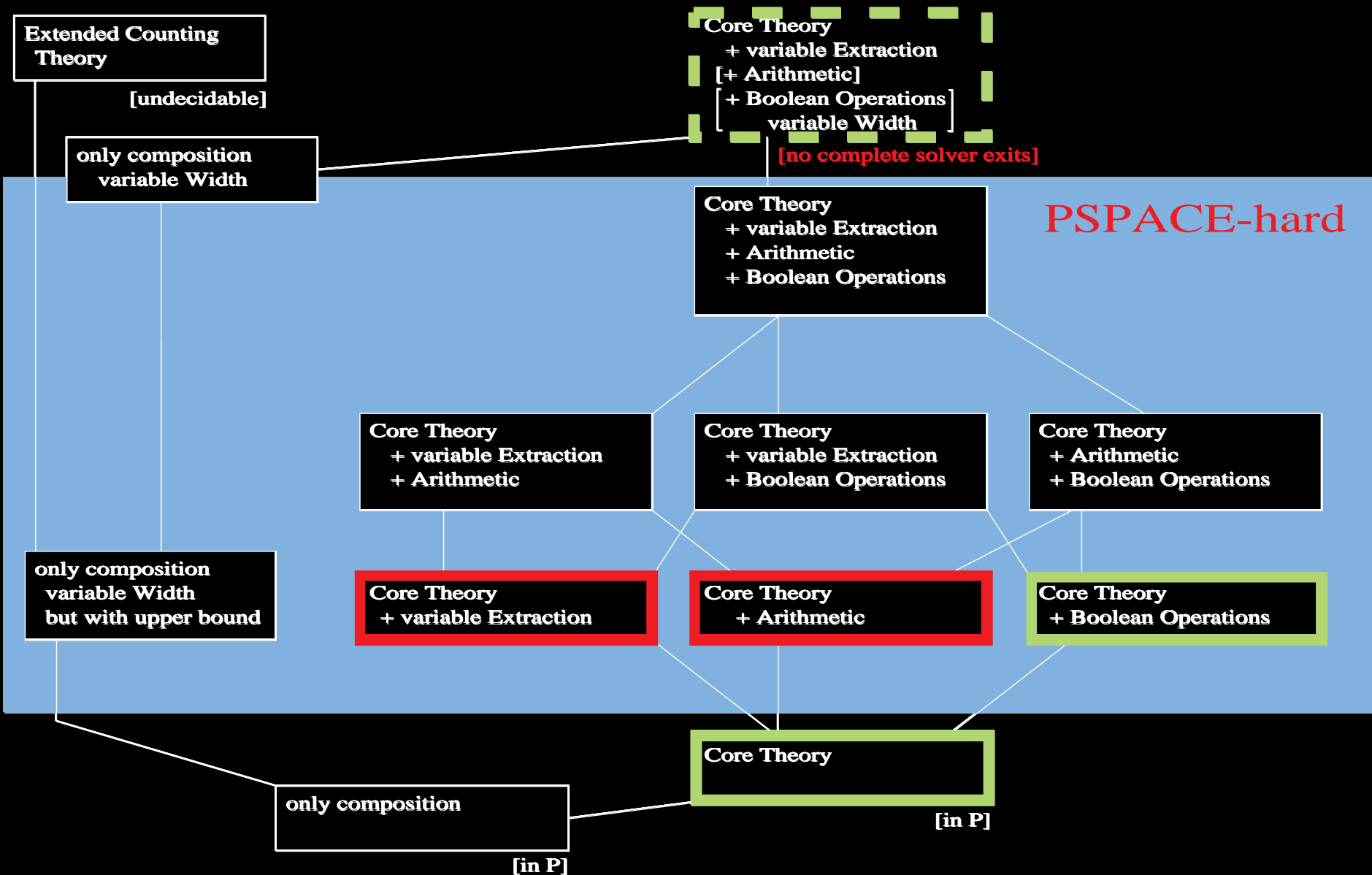
- start with a quantified equation
 $Q_1x_1\dots Q_nx_n. t = u$
- let $S = \text{solve}(t = u)$;
derive $\bigwedge_i x_i = s_i$ where
 - all x_i appear in the right order
 - terms s_i do not refer to x_j with $j > i$
- check for \forall -quantified x_i , whether s_i is *unrestricted*

small overhead
in the size of
the solution
 $\left(\mathcal{O}(|S| \cdot \log |S|) \right)$

\Rightarrow

Solving essentially decides all quantified versions

Complexity Revisited



Summary on Part I

We established

- canonizer and solver for the core theory
- two extensions:
 - boolean operations (canonizer + solver)
 - variable width (solver)
- quantification lemma

Further development?

- high computational complexity
- interesting fragments?
 - \Rightarrow algebraically solvability a serious restriction
- extension of the framework?
 - \Rightarrow seems to boil down to a case-split

Roadmap

Part I Automation in theorem proving: congruence closure

- ★ congruence closure framework
- ★ bit-vector theories
- ★ computational complexity of solving

Part II Automation in model checking: hierarchical decomposition

- ★ model checking and temporal logic
- ★ a technique for temporal scaling
- ★ hierarchical structuring

Part III Automation in concurrency: identifying sequential parts

Model Checking

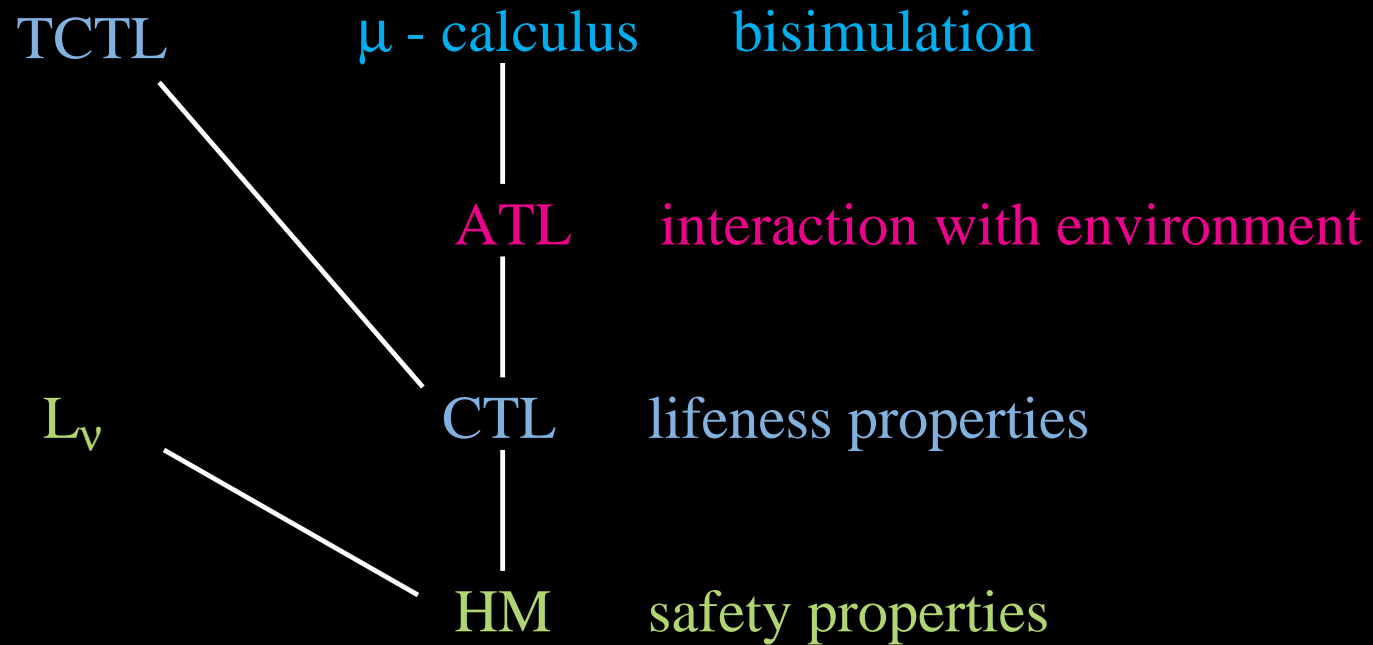
$$M \models \varphi$$

M : description of the system

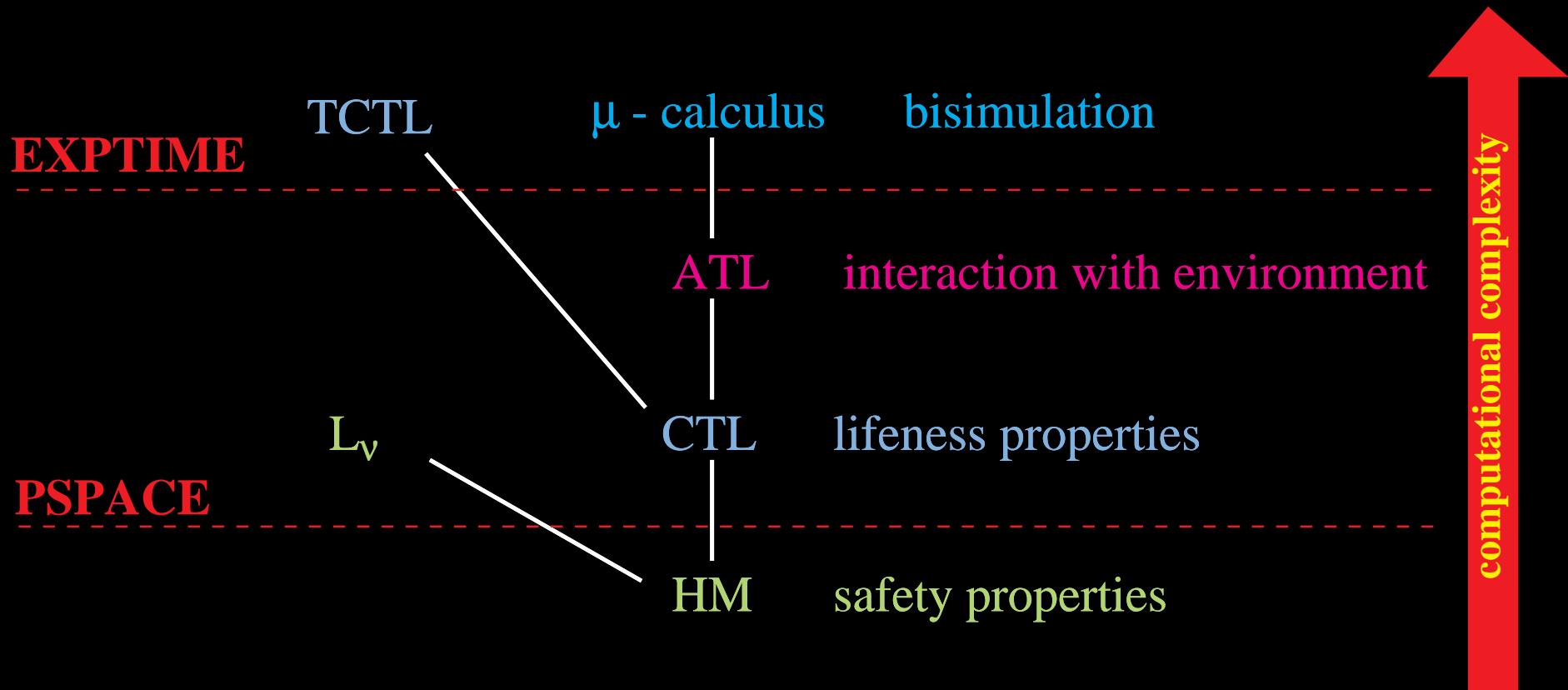
φ : desired property

- easier than proving a general theorem
- completely automatic ('yes' or counterexample)
- efficient algorithms tailored for classes of problems

Temporal Logics



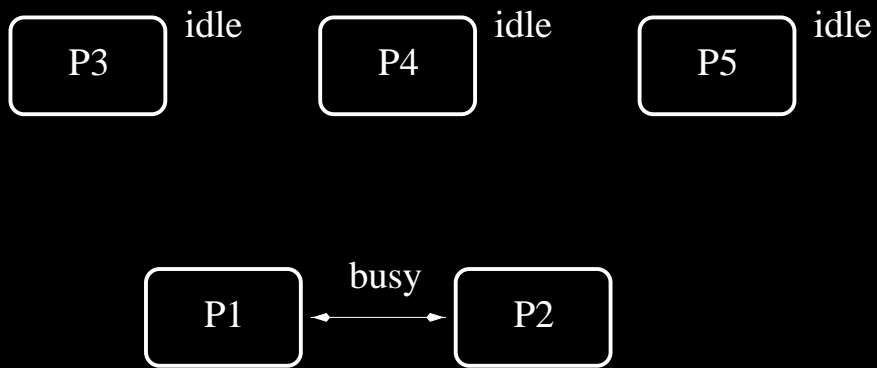
Temporal Logics



Problems with Model Checking

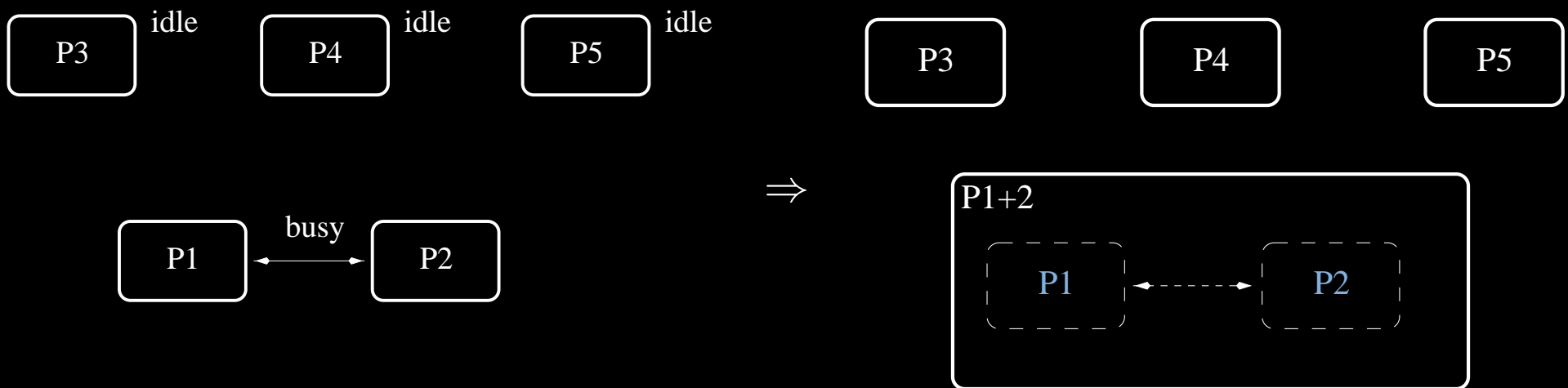
- exponential growth of the state space
⇒ *state explosion problem*
- restricted expressiveness of the model
⇒ experience required to make apt abstractions
- restricted expressiveness of the logics
⇒ properties often have to be *encoded*
- excessive time/space consumption
⇒ heuristics to make *state space exploration* more efficient

Temporal Scaling



$P1 \parallel P2 \parallel P3 \parallel P4 \parallel P5$

Temporal Scaling



Instead of:

$P1 \parallel P2 \parallel P3 \parallel P4 \parallel P5$

Use:

hide busy in $\boxed{P1 \parallel P2} \parallel P3 \parallel P4 \parallel P5$

Model Checking with MOCHA

- parallel execution of components
- communication via shared variables (1 write/multi read)
- *ATL* model checker
- invariant check:
allows temporal scaling via “next” Θ for P
(*Rajeev Alur and Bow-Yaw Wang, CONCUR'99*)
- heuristic to preprocess a system for “next”

Incremental Clustering

input: hypergraph $\mathcal{H} = (\mathcal{C}, \mathcal{E})$

output: forest with leaves \mathcal{C}

PriorityQueue Q

forest := { }

FORALL considered candidates $\mathcal{A} \subseteq \mathcal{C}$

 insert(\mathcal{A} , Q)

WHILE notempty(Q)

$\mathcal{A} := \text{top}(Q)$

 fresh node $\textcircled{\mathcal{A}}$

 forest := forest + ($\textcircled{\mathcal{A}} \mapsto \mathcal{A}$)

 redirect hyperedges: $A_i \in \mathcal{A}$ becomes $\textcircled{\mathcal{A}}$

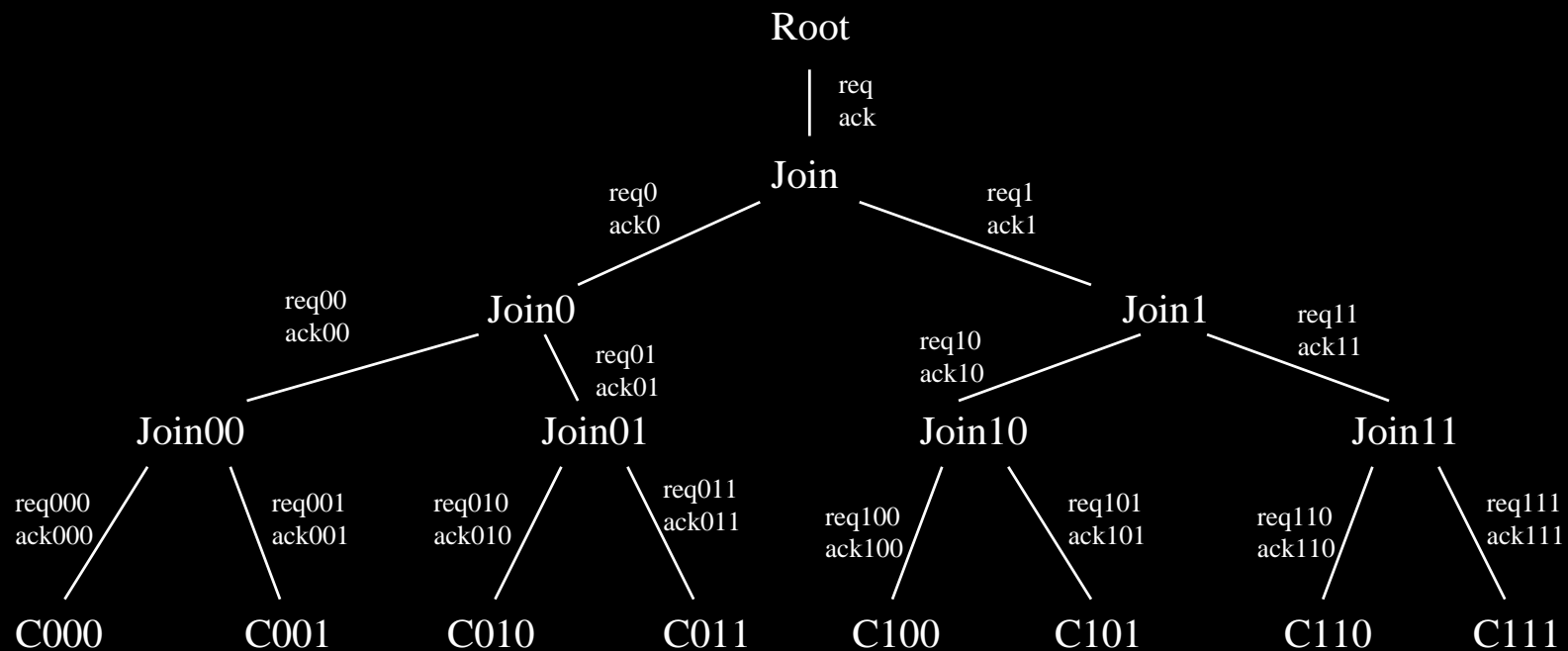
 FORALL $\mathcal{B} \in Q$ with $\mathcal{B} \cap \mathcal{A} \neq \emptyset$

 remove(\mathcal{B} , Q)

 FORALL new candidates \mathcal{D} containing $\textcircled{\mathcal{A}}$

 insert(\mathcal{D} , Q)

Asynchronous Parity Computer

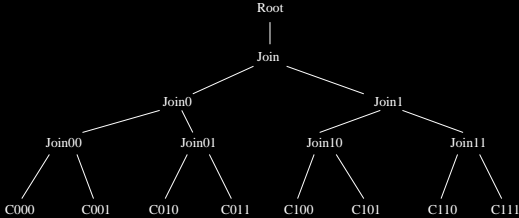
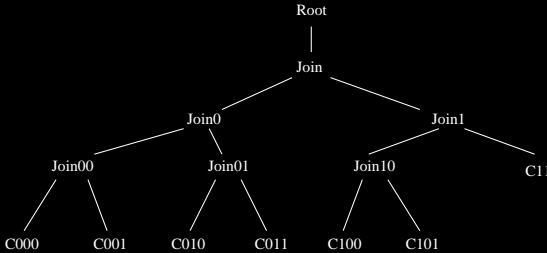
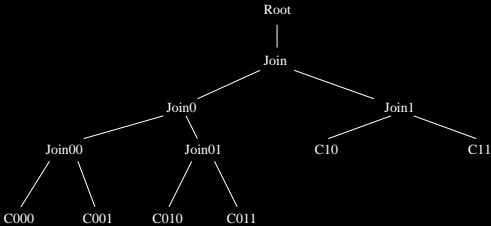
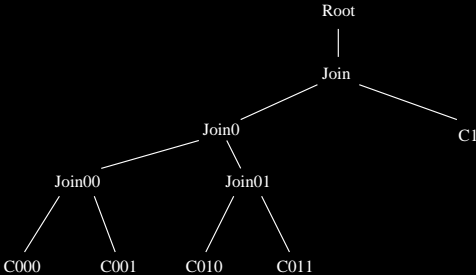
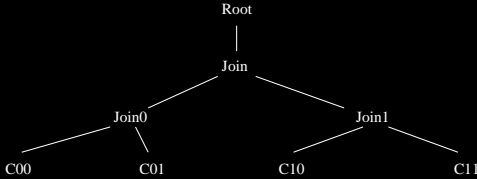
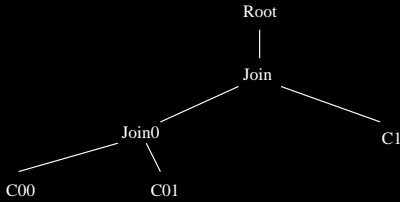


Clients : issue value *true* or *false*

Joins : compute *xor*

Root : acknowledges

Good Heuristic Function



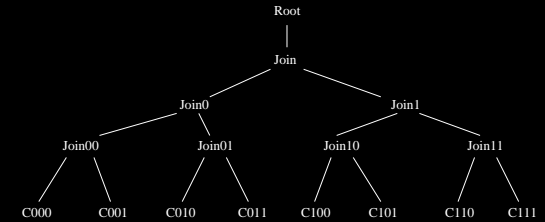
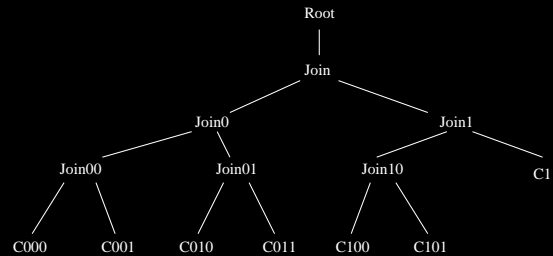
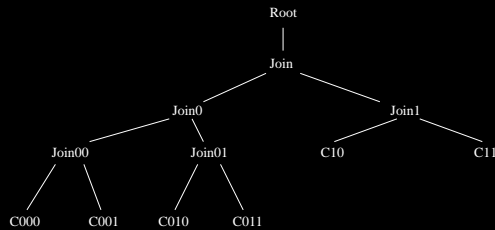
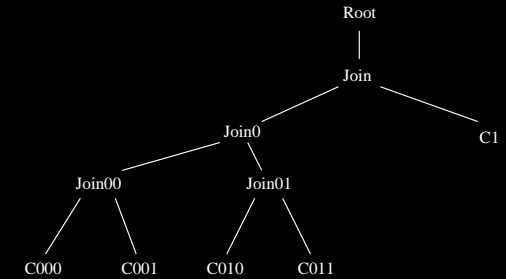
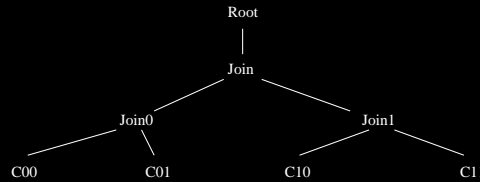
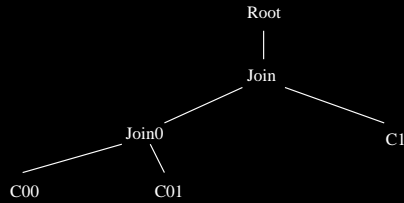
Cover-Number

Size

Egdes

Depth

Good Heuristic Function



$$r_{pref}^+(\mathcal{A}) := \frac{|\{e \in \mathcal{E} \mid e \subseteq \mathcal{A}\}|}{|\mathcal{A}|^2} + \frac{\varepsilon_1}{|\{e \in \mathcal{E} \mid e \cap \mathcal{A} \neq \emptyset\}|} + \frac{\varepsilon_2}{depth(\mathcal{A})}$$

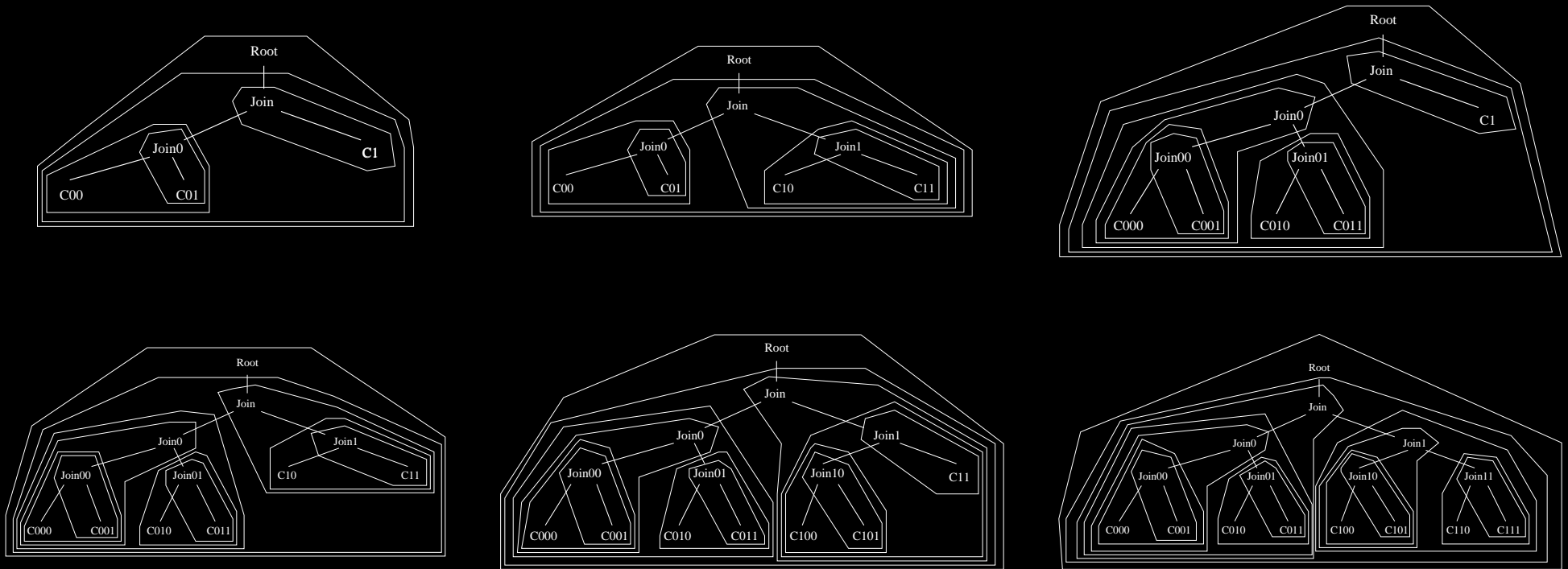
Cover-Number

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Good Heuristic Function



$$r_{pref}^+(\mathcal{A}) := \frac{|\{e \in \mathcal{E} \mid e \subseteq \mathcal{A}\}|}{|\mathcal{A}|^2} + \frac{\varepsilon_1}{|\{e \in \mathcal{E} \mid e \cap \mathcal{A} \neq \emptyset\}|} + \frac{\varepsilon_2}{depth(\mathcal{A})}$$

Cover-Number

Size

Edges

Depth

Summary on Part II

We established

- incremental method for hierarchical decomposition
(has direct application with temporal scaling)
- heuristic function based on 4 criteria:
Cover-Number, Size, Edges, Depth
- sample problem, where this heuristic is well-behaved

Left to do

- validate method/function with other sample topologies
- investigate applicability beyond invariant properties
- (possibly) integration in the next MOCHA release

Guiding Idea

System:

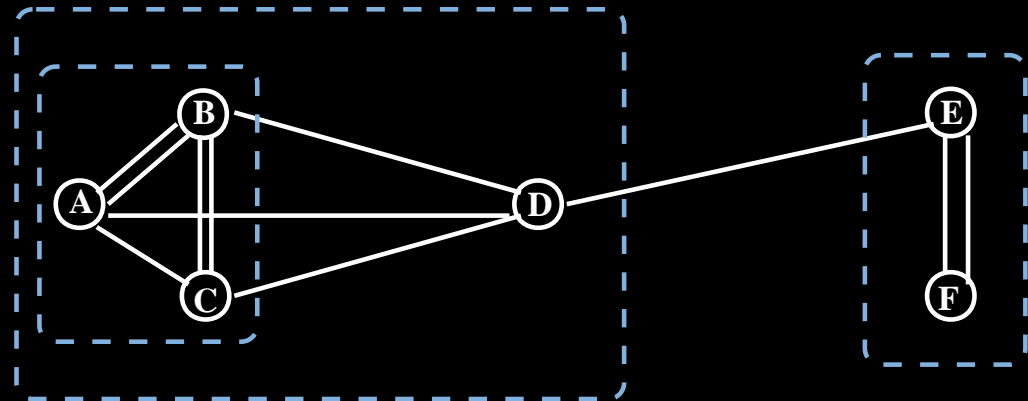
parallel components

Connections:

influence behavior

Structure:

often has *asymmetries*



$\{A, B, C\}$ belong *strongly* together

$\{D, E\}$ are not as “together” as $\{E, F\}$

General Observation:

If we can adapt our analysis to asymmetries, it becomes either

- more expressive
- or • more efficient

We aim to describe, detect and exploit “Togetherness”

Describe Togetherness

Desired Characterization:

$\{A, B\}$ are together [to extend α] $\Leftrightarrow ?$

Likely: the links influence this

Unlikely: link information suffices

Methodologies:

- Identification by categorical models
- *CCS*- or *CSP*-like frameworks
- Properties derived from automata interaction

\Rightarrow If goal too ambitious, restrict to special cases

Detect Togetherness

To be expected: Good characterizations are computationally expensive

⇒ identify typical patterns

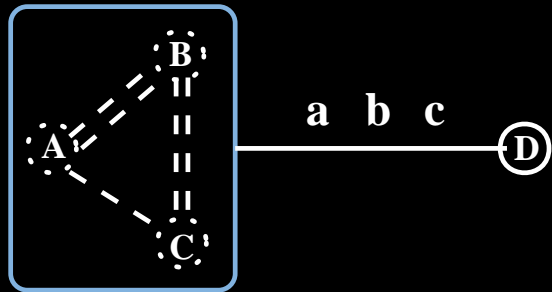
If infeasible, investigate *why*

⇒ lower bounds / hardness results

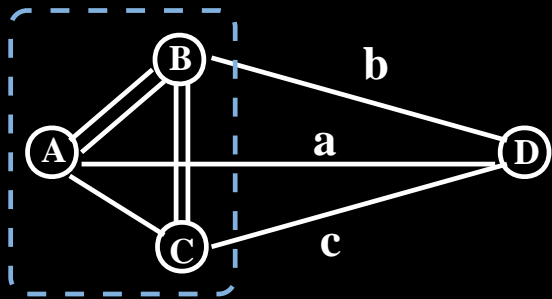
Reasonable hope for *partial* solutions

- develop heuristics (guided search)
- describe special cases

Exploit Togetherness

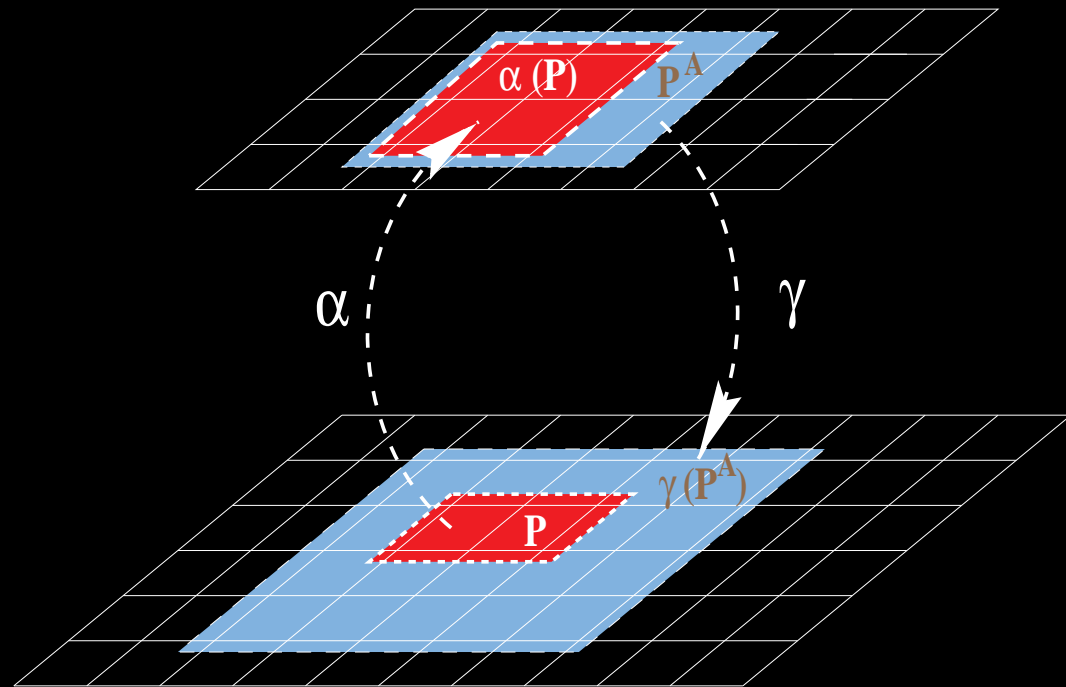


Abstraction



Given System

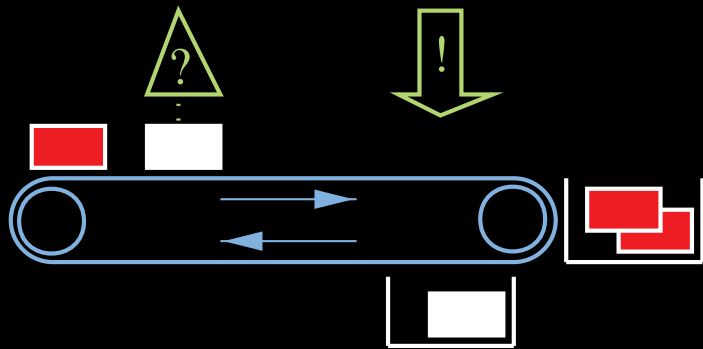
Galois Connection



$$\forall P, P^A : \alpha(P) \subseteq P^A \Leftrightarrow P \subseteq \gamma(P^A)$$

Property holds in abstraction \implies Property holds in actual system

Starting Point: Brick Sorter



Verify controller, running on LEGO® RCX

- Specified as timed automaton (UPPAAL)
- Proven Property: *always will kick off black*

Problem

model checking slow: many delay steps without real progress

Possible solutions

- temporal scaling: \approx 'next Θ for P '
- abbreviations: $1000 a \rightarrow 512 a + 256 a + 128 a + 64 a + 32 a + 8 a$
- building abstraction and prove it correct

Summary

Previous work

- Bit-Vectors: 2 canonizers, 3 solvers, 2 new complexity results
- Model-Checking: heuristic to partition a system hierarchically

} backed with
(experimental)
implementations

Future plans

- Develop a variation of 'next', tailored for timed automata
- Explore the phenomenon of *Togetherness* in concurrent systems in greater detail